SIRIUS Safety Integrated Application Manual Safety relays 3TK28



safety INTEGRATED



SIEMENS

Application Manual

- S.I.A.M. -

Safety relays 3TK28.. Safe load feeder 3RA71. Important notes, contents, safety pilot

3TK282. and 3TK283. relays outputs	
3TK284. electronic outputs	. 2
3TK2845 electronic / relays outputs	3
3TK285. auxiliary relays	- 4
3RA71. safe load feeders	5
Annex	A

This documentation supplements the user manuals of safety relays **3TK28..** and safe load feeders **3RA71.**

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Note

The Safety Functional Examples are not binding and do not claim to be complete regarding the circuits shown, equipping and any eventuality. The Safety Functional Examples do not represent customer-specific solutions. They are only intended to provide support for typical applications. You are responsible in ensuring that the described products are correctly used. These Safety Functional Examples do not relieve you of the responsibility in safely and professionally using, installing, operating and servicing equipment. When using these Safety Functional Examples, you recognize that Siemens cannot be made liable for any damage/claims beyond the liability clause described above. We reserve the right to make changes to these Safety Functional Examples at any time without prior notice. If there are any deviations between the recommendations provided in these Safety Functional Examples and other Siemens publications - e.g. catalogue - then the contents of the other documents have priority.

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General terminology and abbreviations

OUT	The enable circuit is a safety-relevant output (refer to S, S _{el} , S _{ty} and S _{el w}).
K1, K2,	Power contactors or positively-driven contacts (according to IEC 60947) of the power contactors for the feedback circuit of the safety relay.
Sel	Electronic signaling contact
NC contact	NC contact with the function of a signaling output.
NO contact	NO contact with the function of a safety-relevant output (enable circuit).
NOel NOtv , NOel tv	Safety-related solid-state (semiconductor) output (enable circuit). NO contact that opens with a delay (enable circuit)! This contact is required to implement Stop Category 1 acc. to EN 60204-1.
Vs	The supply or operating voltage of safety relays. Comment: +24V DC is always available in the sensor circuit, independent of V s.
€	Positively-opening contacts (acc. to IEC 947-5-1). These are contacts that open as a direct result of a defined movement of an operator element of a switch through elements that are not equipped with springs. For the electrical equipment of machinery, it is mandatory that in all of the safety circuits, opening contacts are always positively-driven.
manual start	For a manual start, an enable signal is generated when the ON button is pressed. This function is also designated as static operation and is specified for EMERGENCY STOP devices (EN 60204-1, conscious action). Safety relays with automatic start can be used up to Category 3: The feedback circuit is statically monitored.
monitored start	For a monitored start, an enable signal is generated when the ON button is pressed. This function is also designated as static operation and is specified for EMERGENCY STOP devices (EN 60204-1, conscious action). <i>Possible with safety relays up to Category 4:</i> <i>The feedback circuit is dynamically monitored.</i>
automatic start	For an automatic start , an enable signal is generated without a manual agreement. This function is also designated as dynamic operation and is not permissible for E Stop devices.
cascading (cascading input)	Safety-relevant single-channel input of a safety relay that is internally evaluated just the same as a sensor signal: Logically AND'ed with other signal encoder inputs. If a voltage is not present, the safety relay safely shuts down the enable circuit (outputs). Operational switching: Depending on the particular safety relay, the enable circuits are switched with a monitored or an autostart (refer to the Safety Navigator 3TK28 in the Attachment)
categories acc. to EN 954-1	Categories B, 1, 2, 3 and 4 are described in EN 954-1:1999 (harmonized Standard in the Machinery Directive): The higher the Category, the higher the fault detection.
safe cable routing acc. to EN 60439-1	Cables with basic insulation may not be routed over sharp edges or should be routed e.g. in steel pipes/ducts (protective Class 2): This is used to exclude faults.
stop categories acc. to EN 60204-1	The Stop Categories represent Stop functions to Stop machinery and equipment in an emergency acc. to IEC 60204-1: 0 = instantaneous, 1 = delayed

Information on using the brochure Symbols that have been used:



Supplementary information



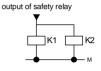
Notes

General notes

Note regarding all of the examples of Category 4 acc. to EN 954-1



Two (or also several) load contactors for Category 4 acc. to EN 954-1 may be connected to a single enable circuit in a control cabinet (a short-circuit as fault can be excluded). Also refer to the Attachment.

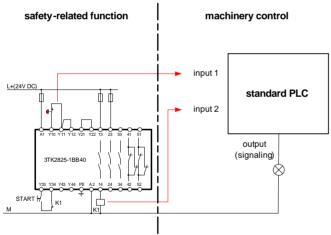


Note for all examples of Category 2 acc. to EN 954-1



With this circuit example, Category 2 according to EN 954-1 can only be fulfilled if, when an actuator fails, either an alarm is automatically generated or the machine control initiates a safe condition:

Otherwise a second shutdown path is required.



category 2 according to EN 954-1

Note regarding safe separation and cable routing



The objective is to achieve a high degree of operational safety. In order to protect against parasitic (vagabond) voltages, the different voltages in a cable or piece of equipment must be insulated against the highest voltage present (protection against electric shock, IEC 61140) **Measure:** Do not route cables with basic insulation along sharp edges or route cables, for example, in a steel pipe or duct (Protective Class 2): This measure is used to exclude faults (the highest degree of insulation).

Table of contents

Note	II
General terminology and abbreviations	III
Information on using the brochure	IV
General notes	IV
Table of contents	V
Table of contents acc. function	XI
Safety pilot	XVI
Homologation 3TK28. / 3RA71	XVIII
Terminal connections 3TK28	XIX
3TK282. 3TK283. Safety relays with relays outputs	1-1
3TK2821	1-2
Category 2 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
Category 2 (acc. EN 954-1) Protective door monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) Protective door monitoring Stop-Category 0	
3TK2821 + 3TK2830	
category 2 (acc. EN 954-1) Protective door monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
categorie 3 (acc. EN 954-1) Protective door monitoring Stop-Category 0	
3TK2822 Category 4 (acc. EN 954-1) Protective door monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) Protective door monitoring stop-category 0	
Category 4 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
3TK2823 + 3TK2830 + 3TK2830	
Category 4 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
3TK2823 + 3TK2856	
Category 4 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
3TK2823 + 3TK2834	
Category 4 (acc. EN 954-1) E-Stop monitoring and two hand monitoring Stop-Category 0	1-13
3TK2823 + 3TK2830 + 3TK2824 + 3TK2824	
Category 4 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
3TK2824	
Category 2 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
3TK2824-1AL20	
Category 2 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
3TK2824	
Category 3 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	
Category 2 (acc. EN 954-1) protective door monitoring Stop-Category 0 Category 3 (acc. EN 954-1) protective door monitoring Stop-Category 0	
3TK2825	
Category 2 (acc. EN 954-1) protective door monitoring Stop-Category 0	
3TK2825-1AL20	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) protective door monitoring Stop-Category 0	1-26

Category 4 (acc. EN 954-1) Protective door monitoring Stop-Category 0	
3TK2825 + 3TK2824 + 3TK2824	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
3TK2825 + 3TK2830 + 3TK2825 + 3TK2825	
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
3TK2827	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 and 1	
Category 3/4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 and 1	
3TK2828	
Category 2 (acc. EN 954-1) Protective door monitoring Stop-Category 0 and 1	
Category 3/4 (acc. EN 954-1) Protective door monitoring Stop-Category 0 and 1	
3TK2828 + 3TK2830 + 3TK2830	
Category 3/4 (acc. EN 954-1) Protective door monitoring Stop-Category 0 and 1	
3TK2834	
Category 4 (acc. EN 954-1) Two hand Monitoring Stop-Category 0	
3TK2834 + 3TK2823	
Category 4 (acc. EN 954-1) E-Stop and Two hand Monitoring Stop-Category 0	
3TK2834	
Category 4 (acc. EN 954-1) E-Stop and Two hand Monitoring Stop-Category 0	
3TK2834 + 3TK2835	
Category 4 (acc. EN 954-1) Two hand Monitoring with run-on distance check Stop-Category 0	
3TK284. Safety relays with electronic outputs	
3TK2840	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	2-2
Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	2-3
Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
3TK2840 + 3TK2830 + 3TK2830	
Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
3TK2840	
Category 3 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0	
3TK2841	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) Light grid Monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) safety mat Monitoring Stop-Category 0	
3TK2841 + 3TK2830	
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
3TK2841 + 3TK2830 + 3TK2830	
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
3TK2841 + 3TK2856	
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
3TK2841 + 3TK2857	
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 and 1	
3TK2841 + 3TK2841 + 3TK2841	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	2-20

Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	2-21
3TK2842	2-22
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 and 1	2-22
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 and 1	2-23
Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 and 1	2-24
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 and 1	2-25
Category 4 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0 and 1	2-26
Category 4 (acc. EN 954-1) Light grid Monitoring Stop-Category 0 and 1	2-27
Category 3 (acc. EN 954-1) Safety mat Monitoring Stop-Category 0 and 1	2-28
3TK2842 + 3TK2830 + 3TK2830	2-29
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 and 1	2-29
3TK2842 + 3TK2841	2-30
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 and 1	2-30
3TK2845 Safety relays with relays and electronic outputs	3-1
3TK2845	3-2
Category 2 (acc. EN 954-1) E-Stop and protective door Monitoring Stop-Category 0	3-2
Category 4 (acc. EN 954-1) E-STOP and Protective door Monitoring Stop-Category 0	3-3
Category 2 (acc. EN 954-1) E-Stop and protective door Monitoring Stop-Category 0 and 1	3-4
Category 4 (acc. EN 954-1) E-Stop and protective door Monitoring Stop-Category 0 and 1	3-5
Category 4 (acc. EN 954-1) E-Stop and Light grid Monitoring Stop-Category 0	3-6
Category 4 (acc. EN 954-1) E-Stop and Light grid Monitoring Stop-Category 0 and 1	3-7
Category 2 (acc. EN 954-1) E-Stop and protective door Monitoring Stop-Category 0 and 1	3-8
Category 4 (acc. EN 954-1) E-Stop and protective door Monitoring Stop-Category 0 and 1	3-9

3TK285. Safety relays with auxiliary relays	4-1
3TK2850	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
3TK2850-1LA20	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
3TK2850	
Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
3TK2850 + 3TK2830	
Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
3TK2850 + 3TK2830 + 3TK2830	
Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
3TK2850 + 3TK2856	
Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
3TK2850	
Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
3TK2850-1LA20	
Category 3 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0	
3TK2851	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0	
3TK2852	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) Protective door Monitoring Stop-Category 0	
3TK2853	
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0	
Category 4 (acc. EN 954-1) Magnet sensor Monitoring Stop Category 0	
Category 4 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0	
Category 3 (acc. EN 954-1) Safety mat Monitoring Stop-Category 0	
3TK2853 + 3TK2856	
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	
3TK2853 + 3TK2857	
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0	

3RA71. Safe load feeders	5-1
3RA7100AL2	5-2
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	5-2
Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0	5-3
Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	5-4
Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0	5-5
Category 3 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0	5-6
3RA711	5-7
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	5-7
Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0	5-8
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	5-9
Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0	. 5-10
Category 4 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0	. 5-11
Category 3 (acc. EN 954-1) Safety mat Monitoring Stop-Category 0	. 5-12
Category 4 (acc. EN 954-1) Light grid Monitoring Stop-Category 0	. 5-13
3RA711 + 3RA712 + 3TK2841 + 3TK2853	. 5-14
Category 4 (acc. EN 954-1) E-STOP Monitoring Protective door Monitoring Stop-Category 0	. 5-14

ANNEX	A-1
Categories acc. to EN 954-1	A-2
Serial connection	A-8
E-STOP command element	A-8
protective door monitoring	A-9
E-Stop command element and protective door monitoring	A-10
Manual start, monitored start and auto start	A-11
Safety-relevant (protected) routing, safe separation	
Protective door monitoring with tumbler mechanism	A-12
One output for category 3 and 4 with two switch gears	A-12
Technical Assistance for low-voltage switchgear	A-13
NOTICES	A-14

Table of contents acc. function

E-Stop Monitoring, Stop-Category 0

Category 2		
	3TK2821	1-2
	3TK2821 + 3TK2830	
	3TK2824	1-15
	3TK2824-1LA20	1-16
	3TK2825 + 3TK2824 + 3TK2824	1-28
	3TK2840	2-2
	3TK2841	2-8
	3TK2841 + 3TK2841 + 3TK2841	2-20
	3TK2850	4-2
	3TK2850-1LA20	4-3
	3TK2851	4-11
	3TK2852	4-16
	3TK2853	4-21
	3RA710	5-2
	3RA710	5-7
Category 3	_	
	3TK2821	1-3
	3TK2821 + 3TK2830	1-7
	3TK2824	1-18
	3TK2824-1LA20	1-17
	3TK2840	2-3
	3TK2841 + 3TK2841 + 3TK2841	2-21
	3TK2850	4-5
	3TK2850 + 3TK2830	4-6
	3TK2850 + 3TK2830 + 3TK2830	4-7
	3TK2851	4-13
	3TK2852	4-18
	3RA710	5-4
Category 4		
	3TK2823	1-10
	3TK2823 + 3TK2830 + 3TK2830	1-11
	3TK2823 + 3TK2856	1-12
	3TK2823 + 3TK2830 + 3TK2824 + 3TK2824	1-14
	3TK2825-1LA20	1-24
	3TK2825 + 3TK2830 + 3TK2825 + 3TK2825	1-29
	3TK2841	2-9
	3TK2841 + 3TK2856	2-17
	3TK2853	4-23
	3TK2853 + 3TK2856	4-23
	3RA710	5-7

E-Stop Monitoring, Stop-Category 0 and 1

Category 2		
	3TK2827	1-30
	3TK2842	2-22
Category 3		
	3TK2827	1-31
Category 4		
	3TK2842	2-23

Category	2	
_outogory /	3TK2840 + 3TK2830 + 3TK2830	2-6
	3TK2845	3-2
Category	4	
	3TK2845	3-3
E-Stop and Protect	ive door Monitoring, Stop-Category 0 and 1	
Category	2	
0,	3TK2840 + 3TK2830 + 3TK2830	2-6
	3TK2845	3-4
Category		
	3TK2845	3-5
E-Stop and Light gi	rid Monitoring, Stop-Category 0	
Category	4	
_outogory	3TK2845	3-6
	rid Manifestra Stan Ostanov Ostal 1	
E-Stop and Light gi	rid Monitoring, Stop-Category 0 and 1	
1 3 3		
Category	4	

Protective door-Monitoring, Stop-Category 0

Category 2		
	3TK2821	1-4
	3TK2821 + 3TK2830	
	3TK2824	1-19
	3TK2825	1-21
	3TK2840	2-4
	3TK2841	2-10
	3TK2841 + 3TK2841 + 3TK2841	2-20
	3TK2850	4-4
	3TK2851	4-12
	3TK2852	4-17
	3TK2853	4-22
	3RA710	5-3
	3RA710	5-8
Category 3		
	3TK2821	1-5
	3TK2821 + 3TK2830	1-8
	3TK2824	1-20
	3TK2840	2-5
	3TK2850	4-9
	3TK2851	4-14
	3TK2852	4-19
	3RA710	5-5
Category 4		
	3TK2822	1-19
	3TK2824	1-10
	3TK2825-1LA20	1-26
	3TK2825 + 3TK2830 + 3TK2825 + 3TK2825	1-29
	3TK2841	2-11
	3TK2841 + 3TK2830	2-15
	3TK2841 + 3TK2830 + 3TK2830	2-16
	3TK2841 + 3TK2856	2-18
	3TK2853	4-24
	3TK2853 + 3TK2857	4-29
	3RA710	5-10

Protective door Monitoring, Stop-Category 0 and 1

Category 2		
	3TK2828	1-32
	3TK2842	2-22
Category 3		
	3TK2828	1-33
	3TK2828 + 3TK2830 + 3TK2830	1-34
Category 4		
	3TK2828 + 3TK2830 + 3TK2830	1-34
	3TK2841 + 3TK2857	2-19
	3TK2842	2-25

Magnet sensor Monitoring, Stop-Category 0

Category 3		
	3TK2840	2-7
	3TK2851	4-15
	3TK2852	4-20
Category 4		
	3TK2841	2-12
	3TK2842	2-26
	3TK2853	4-25
	3RA710	5-11

Light grid Monitoring, Stop-Category 0

4-15 4-20
4-20
2-13
2-27
4-26
5-13

Safety mat Monitoring, Stop-Category 0

Category 3		
	3TK2841	2-14
	3TK2842	2-28
	3TK2853	4-27
	3RA710	5-12
Two hand Monitorin	ng, Stop-Category 0	
Category 4		
	3TK2834	1-35
Two hand Monitorin	ng with run-on distance check , Stop-Category 0	
Category 4		
	3TK2834 + 3TK2835	1-38

Two hand Monitoring and E-STOP Monitoring, Stop-Category 0

Category 4

3TK2834
3TK2834 + 3TK2823

3TK28	
pilot	
Safety	

I		011.05=													
	٧s	230 A AC					×	×		×		×	×	×	
	supply voltage V _s	J15V AC					×	×		×		×	×	×	
	su volt	24 A AC		×	×	×	×	×		×		×	×	×	×
		24V DC		×	×	×	×	×		×		×	×	×	×
	signaling output			1NC				2NC		1NC		1NC		2NC	1NC
	safety-related OUT OUT el.														
	safety OUT			3NO	2NO	2NO	2NO	3NO	2NO+2N	ot_v	2NO+	$2NOt_{v}$	4NO	2NO	3NO
	IS	operational switching													
	funtions	autostart / monitore start		- / ×	- / X	×/-	- / X	x / x		- / ×		- / X			
		gnibesses													
	stop-category EN 60204-1	L								×		×			
		0		×	х	×	х	х		х		×	х		
		Erweiterung											×		
		g∍wîusldosN													×
		bnsh owt												x	
	rs	tem toetnoo													
31K282./31K283.	sensors	sensor sensor													
. / .		light curtain / grid													
282		protective door		×	×		×	×				×			
31K		Got2-3	itput	×		×	×	×		×					
	ج ب	4	IN OL		×	×		×							
H	category EN 954-1	3	rela	×	×	×	×	×		×		×			
olic	ca: EN	5	with	×			×	×		×		×			
Safety pilot		safety relay	safety relays with relay output	3TK2821	3TK2822	3TK2823	3TK2824	3TK2825		3TK2827		3TK2828	3TK2830	3TK2834	3TK2835

el. = safety-related electronic (semiconductor) outpout OUT = safety-related output (contact, relay) $t_{\rm v}$ = timed delayed output (stop-category 1)

NO = normally open contact / output NC = normally closed

Safety pilot 3TK28

		230 V AC								×	×	×					×			
	y Vs	DA Verr		_				-		×	×	×					×			
	supply voltage Vs	24 A PC		_				-		×	×	×					×			
	Ň	24V DC		×	×	×		×		×	×	×	×	×	×		×	×	×	×
	signaling output							1 el.		SIRIUS	1NO SIRIUS	1NO SIRIUS	SIRIUS	1NO SIRIUS	SIRIUS		SIRIUS	SIRIUS	SIRIUS	SIRIUS
	safety-related DUT OUT el.			2 ¹⁾	2	$1+1 t_v$		2					1	1	1			1	1	-
	safety- OUT							2NO		3NO	2NO	6NO	3NO	ON9	3NO _t v		3NO	3NO	3NO	3NO _{tv}
	S	operational switching			x ³⁾	(° X		x ²⁾					×	×	×			x	×	×
	funtions	autostart / monitore start		×/×	x / x	x/x		×/×		x / x	x / x	x / x	x / x				x / x	x / x		
		gnibecsec			х ³⁾	(c X		X ²⁾					x	×	×			x	×	×
	stop-category EN 60204-1	L				×		×							×					×
		0		×	×	×		×		×	×	×	×	×			×	×	×	
		gnunstiswn3												×	×				×	×
		g∍wîusldosN																		
		bnsh owt					S													
Ä	6	tem tostnoo		×	x	×	utput	×		х	х	х	х				х	х		
281619 p1101 51K284. / 31K282. / 3KA / 1	sensors	tensor sensor	nductor) outputs	×	×	×	or) / relay outputs	×		×	×	×	×				×	×		
		light curtain / grid	ducto	×	×	×	nductor)	×		×	×	×	×				×	×		
./.3		protective door		×	×	×		×	acts	×	×	×	×				×	×		
707		qot2-3	ic (se	×	×	×	ic (se	×	/ cont	×	×	×	×				×	×		
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5	category EN 954-1	3) ele	×	×	×	n elec	×	<mark>xne</mark> (×	×	×	×				×	×		
5	са EN	5	with	×	x	×	with	×	with	×	×	×	х			ders	x	×		
Salety		relay səfety	safety relays with electronic (semico	3TK2840	3TK2841	3TK2842	safety relays with electronic (semico	3TK2845	safety relays with auxiliary contacts	3TK2850	3TK2851	3TK2852	3TK2853	3TK2856	3TK2857	safe load feeders	3RA710	3RA711	3RA712	3RA713/4

el. = safety-related electronic (semiconductor) outpout OUT = safety-related output (contact, relay) tv = timed delayed output (stop-category 1)

NO = normally open contact / out NC = normally closed SIRIUS = using SIRIUS accessories

using of positively-driven actuators is required
 operational switching is possible by using the cascading input 1
 operational switching with autostart or monitored start

(depending on the selected start function of the safety relay)

Homologation 3TK28. / 3RA71.

Device	BG	TÜV	UL	CSA	AOPD EN 61496-1	Feuerungstechnik VDE 0116 (Burning technology)	EN 954-1	IEC 61508
3TK2821	Х		Х	Х			Х	
3TK2822	Х		Х	Х			Х	
3TK2823	Х		х	Х			Х	
3TK2824	Х		Х	Х			Х	
3TK2825	Х		Х	Х			Х	
3TK2827	Х		х	Х			Х	
3TK2828	Х		х	Х			Х	
3TK2830	Х		х	Х			Х	
3TK2834	Х		х	Х			Х	
3TK2835	х		х	Х			Х	
3TK2840		х	х	Х			Х	Х
3TK2841		Х	х	Х	Х	Х	Х	Х
3TK2842		Х	х	Х	Х	Х	Х	Х
3TK2845		Х	Х	Х	Х		Х	Х
3TK2850		х	х	Х			Х	Х
3TK2851		х	х	Х			Х	Х
3TK2852		х	х	Х			Х	Х
3TK2853		Х	х	Х	Х		Х	Х
3TK2856		х	х	Х			Х	Х
3TK2857		х	х	Х			Х	Х
3RA710		х	х	Х			Х	Х
3RA711		х	х	Х	Х		Х	Х
3RA712		Х	х	Х			X	Х
3RA713/4		х	х	Х			Х	Х

Terminal connections 3TK28

Safety-relays 3TK282.

clamp	function	3TK2821	3TK2822	3TK2823	3TK2824 24V	3TK2824 115V / 230V	3TK2825	3TK2827/28
A1	Power supply L/+	Х	Х	х	Х	Х	Х	х
A2	Power supply N/-	Х	Х	Х	Х	Х	Х	Х
Y1, Y2	Feedback circuit / ON button between Y1-Y2	Х			х			
Y10	Sensor circuit 1 one-channel between Y10 – Y11, bridge between Y11 – Y12 and Y21 – Y22						Х	Х
Y11, Y12	Sensor circuit 1 between Y11 – Y12		X ¹⁾	X ¹⁾		Х	X ²⁾	X ²⁾
Y21, Y22	Sensor circuit 2 between Y21 – Y22		X1)	X ¹⁾		X ³⁾	Х	Х
Y33, Y34	Feedback circuit, ON button between Y33 – Y34		Х	Х		Х	Х	Х
Y43, Y44	Auto start, bridge between Y43 – Y44; monitored start, without bridge.						X	
13-14 23-24 33-34	Enable circuit S: instantaneous	X X X	X X	X X	X X	X X	X X X	X X
47-48 57-58	Enable circuit Stv: delayed							X X
31-32 41-42 51-52	Signaling contacts Ö	х					x x	Х

¹⁾ The safety relay can only be used for two-channel sensors.

²⁾ For tow-channel sensors, bridge between Y10 – Y11

³ For one-channel sensors to Y11 – Y12, bridge between Y21 – Y22

Safety-relays 3TK284. / 3TK285. / 3RA71.

Clamp	Function	3TK2840	3TK2841	3TK2842	3TK2850,51,52 3RA710*	3TK2853 3RA711*	3TK2856,57
A1	Power supply L/+	Х	Х	Х	Х	Х	Х
A2	Power supply N/-	Х	Х	Х	Х	Х	Х
1	Cascading input, start with positive voltage		Х	Х		Х	Х
3	Operational switching, (+24V supply for sensor ,operational switching*)					Х	Х
4	Operational switching, input					Х	Х
Y11, Y12	Sensor circuit 1 between Y11 – Y12	Х	Х	Х	Х	Х	
Y20	One-channel operation when a jumper to Y21 is inserted	Х			Х		
Y21, Y22	Sensor circuit 2 between Y21 – Y22	Х	Х	Х	Х	Х	
Y32	Auto start when supplied with +24V		Х	Х		Х	
Y33	Feedback circuit between Y33 – Y34 for automatic start	Х			Х		
Y33	Feedback circuit, ON button (+24V supply for feedback circuit, On button)					Х	
Y34	Feedback circuit , ON button Input supplied by +24V	Х	Х	Х	Х	Х	
Y35	Without cross-circuit fault detection for supply with a positive voltage		Х	Х		Х	
2	Safety solid-state output					X	Х
14 24	Safety solid-state output Enable circuit Sel: instantaneous	X X	X X	Х			
28	Safety solid-state output Enable circuit Sel tv: delayed			Х			

Safety-relays 3TK2845

Clamp	Function	3ТК2845
A1	Power supply +	Х
A2	Power supply -	Х
1	Cascading input (automatic start), start with positive voltage	Х
Y11	Sensor 1 circuit 1, output (test signal)	Х
Y12	Sensor 1 circuit 1, input monitored start	Х
Y21	Sensor 1 circuit 2, output (test signal)	Х
Y22	Sensor 1 circuit 2 input monitored start	Х
Y34	On button input	Х
Y35	Cross-circuit fault detection sensor 1	Х
Y41	Sensor circuit 1, output (test signal)	Х
Y42	Sensor 2 circuit 1, input automatic start	Х
Y51	Sensor 2 circuit 2, output (test signal)	Х
Y52	Sensor 2 circuit 2, input automatic start	Х
Y64	Feedback circuit to plus	Х
Y65	Cross circuit detection Sensor 2	Х
Y72	Sensor 3 key switch circuit 1, Input	Х
Y82	Sensor 3 key switch circuit 2, Input	Х
13-14 37-38	Enable circuit (S, Stv: depending on device type)	Х
24 48	Safety solid-state output (Sel, Sel tv: acc. device type)	X
52	Electronic solid-state signaling output	Х

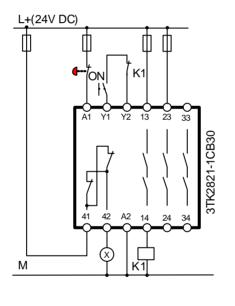
3TK282. 3TK283.

Safety relays with relays outputs



3TK2821

Category 2 (acc. EN 954-1) E-Stop monitoring Stop-Category 0 3NO 1NC Vs 24 V DC manual start







Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit. The user must ensure that these types of faults do not occur.

 $\mathbf{\Lambda}$

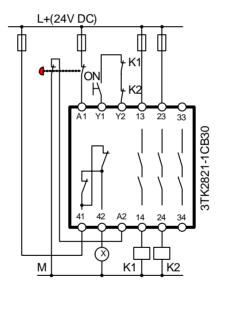
Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively opening contacts may be used as sensors.

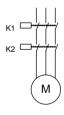
Using this circuit example, Category 2 according to EN 954-1 can only be fulfilled, if, when the actuator fails, either an alarm is automatically generated or the machine control initiates a safe condition. Otherwise a second shutdown path is required.

3TK2821

Category 3 (acc. EN 954-1) E-Stop monitoring Stop-Category 0 3NO 1NC Vs 24 V DC manual start









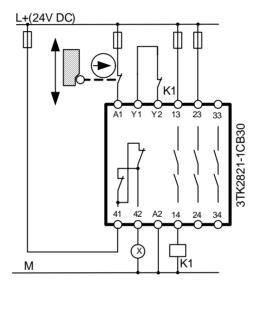
Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit. The user must ensure that these types of faults do not occur.

 $\mathbf{\Lambda}$

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 4 according to EN 954-1 can be achieved with supplementary measures, e.g. by routing cables in a safety-relevant fashion.

1	3TK2821	Category 2 (acc. EN 954-1) Protective door monitoring Stop-Category 0	3NO 1NC Vs 24 V DC auto start
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Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit. when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.

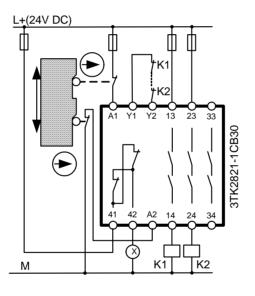
Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively opening contacts may be used as sensors.

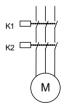


Using this circuit example, Category 2 according to EN 954-1 can only be fulfilled, if, when the actuator fails, either an alarm is automatically generated or the machine control initiates a safe condition. Otherwise a second shutdown path is required.

3TK2821

Category 3 (acc. EN 954-1) Protective door monitoring Stop-Category 0 3NO 1NC Vs 24 V DC auto start







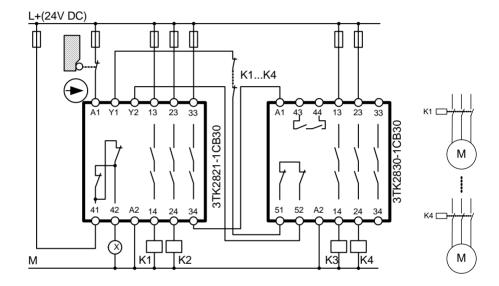
Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit. when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.

 $\mathbf{\Lambda}$

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 4 according to EN 954-1 can be achieved with supplementary measures, e.g. by routing cables in a safety-relevant fashion.

3TK2821 + 3TK2830	Category 2 (acc. EN 954-1)	6NO 1NC
•••••••••••••••••	Protective door monitoring	Vs 24 V DC
	Stop-Category 0	auto start





Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit, when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.



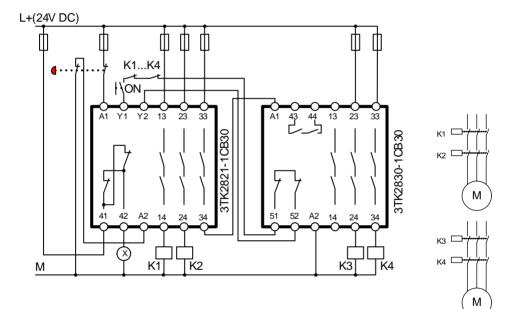
Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively opening contacts may be used as sensors.

Using this circuit example, Category 2 according to EN 954-1 can only be fulfilled, if, when the actuator fails, either an alarm is automatically generated or the machine control initiates a safe condition. Otherwise a second shutdown path is required.

Up to eight 3TK2830 expansion devices may be connected to an FK (enable circuit) of the basic 3TK2821 device.

If several expansion devices are cascaded, then the response times must be added. If faults can be excluded – such as a P fault or M fault – then it is permissible to control an expansion device (cascading) through one channel. This is always fulfilled within a control cabinet or when connecting cables are routed in a protected fashion.

3TK2821 + 3TK2830	Category 3 (acc. EN 954-1)	6NO 1NC
	E-Stop monitoring	Vs 24 V DC
	Stop-Category 0	manual start





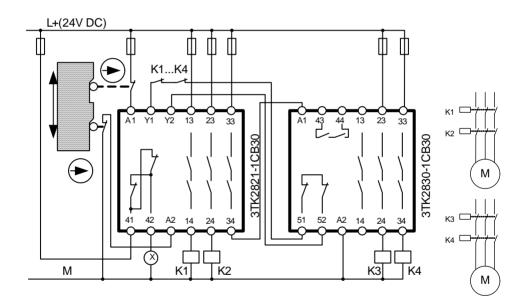
Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit. when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Up to eight 3TK2830 expansion devices may be connected to an FK (enable circuit) of the basic 3TK2821 device.

If several expansion devices are cascaded, then the response times must be added. If faults can be excluded – such as a P fault or M fault – then it is permissible to control an expansion device (cascading) through one channel. This is always fulfilled within a control cabinet or when connecting cables are routed in a protected fashion. 3TK2821 + 3TK2830Category 3 (acc. EN 954-1)6NO 1NCProtective door monitoringVs 24 V DCStop-Category 0auto start





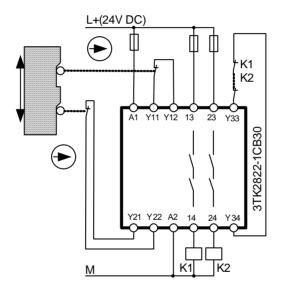
Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit, when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.

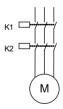
⚠

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

If several expansion devices are cascaded, then the response times must be added. If faults can be excluded – such as a P fault or M fault – then it is permissible to control an expansion device (cascading) through one channel. This is always fulfilled within a control cabinet or when connecting cables are routed in a protected fashion.

3TK2822	Category 4 (acc. EN 954-1) Protective door monitoring Stop-Category 0	2NO Vs 24 V DC auto start







The safety relay can only be used for two-channel sensors.

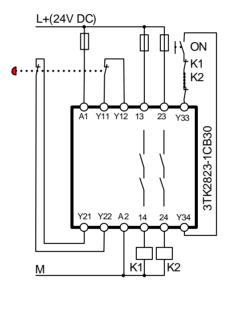
⚠

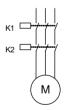
Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively opening contacts may be used as sensors.

For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).

3TK2823

Category 4 (acc. EN 954-1) E-Stop monitoring Stop-Category 0 2NO Vs 24 V DC monitored start



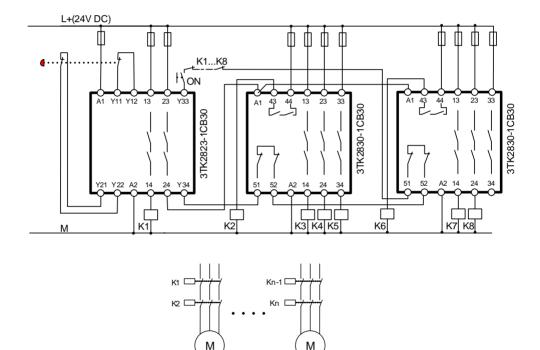




The safety relay can only be used for two-channel sensors.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors. For Category 4, several EMERGENCY STOP commanding devices may be connected in series. 3TK2823 + 3TK2830 + 3TK2830 Category 4 (acc. EN 954-1) E-Stop monitoring Stop-Category 0 9NO Vs 24 V DC monitored start





Up to eight 3TK2830 expansion devices may be connected to an FK (enable circuit) of the basic 3TK2821 device.

The safety relay can only be used for two-channel sensors.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

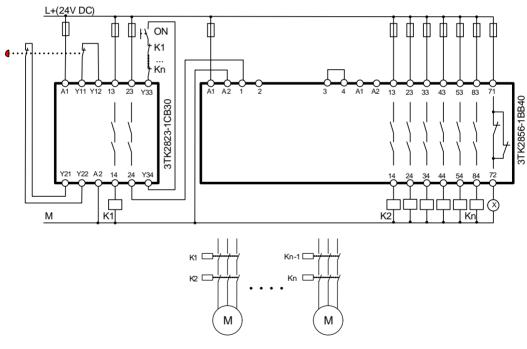
If several expansion devices are cascaded, then the response times must be added. If faults can be excluded – such as a P fault or M fault – then it is permissible to control an expansion device (cascading) through one channel. This is always fulfilled within a control cabinet or when connecting cables are routed in a protected fashion.

For Category 4, several EMERGENCY STOP commanding devices may be connected in series.

 3TK2823 + 3TK2856
 Category 4 (acc. EN 954-1)
 7N

 E-Stop monitoring Stop-Category 0
 mm

7NO 1NOel. 1NC Vs 24 V DC monitored start





The safety relay can only be used for two-channel sensors.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

If faults can be excluded – such as a P fault or M fault – then it is permissible to control an expansion device (cascading) through one channel. This is always fulfilled within a control cabinet or when connecting cables are routed in a protected fashion.

For Category 4, several EMERGENCY STOP commanding devices may be connected in series.

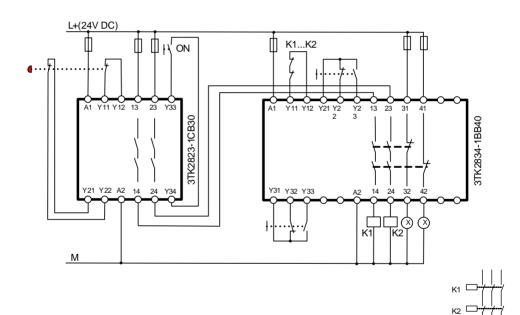
SIRIUS Safety Integrated Application Manual – S.I.A.M. – Edition 02/2005

 3TK2823 + 3TK2834
 Category 4 (acc. EN 954-1)
 2NO 2NC

 E-Stop monitoring and
 Vs 24 V DC

 two hand monitoring
 monitored start

 Stop-Category 0
 No 2NC





The safety relay 3TK2823 can only be used for two-channel sensors.

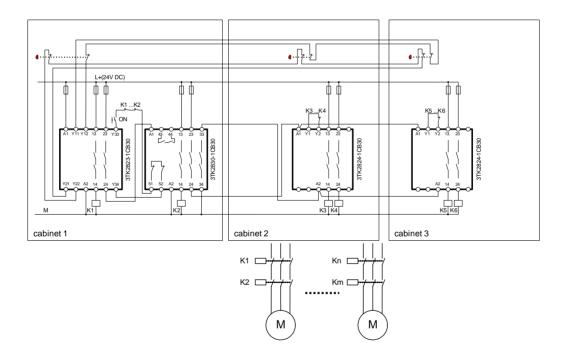


Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

For Category 4, several EMERGENCY STOP commanding devices may be connected in series.

Μ

	Safety relay	Function	Comments
1	3TK2823 + 3TK2830 + 3TK2824 + 3TK2824	Category 4 (acc. EN 954-1) E-Stop monitoring Stop-Category 0	6NO Vs 24 V DC monitored start
		3 Switchboards 3 E-Stop When an Emergency Stop button is pressed, all of the 3TK28 device in the switchboard shut up	





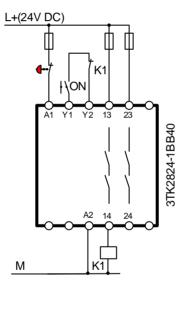
The safety relay can only be used for two-channel sensors. EMERGENCY STOP commanding devices are monitored by a 3TK28 in cabinet 1: When an EMERGENCY STOP commanding device is actuated, all of the actuators in the cabinets are shut down. The actuators of a cabinet are monitored by the associated 3TK28.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

For Category 4, several EMERGENCY STOP commanding devices may be connected in series.

Category 2 (acc. EN 954-1) E-Stop monitoring Stop-Category 0 2NO Vs 24 V DC manual start







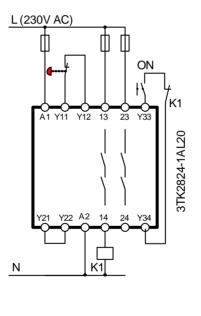
Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit. when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

3TK2824-1AL20

Category 2 (acc. EN 954-1) E-Stop monitoring Stop-Category 0 2NO Vs 230 V AC manual start







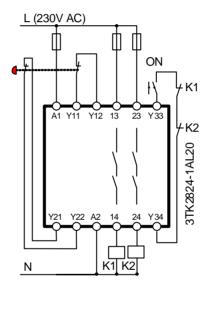
Not all faults are detected in the sensor circuit - e.g. a P fault in Y11 Y12 circuit, M fault in the Y21 Y22 circuit, when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.

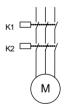
Λ

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

3TK2824-1AL20

Category 3 (acc. EN 954-1) E-Stop monitoring Stop-Category 0 2NO Vs 230 V AC manual start



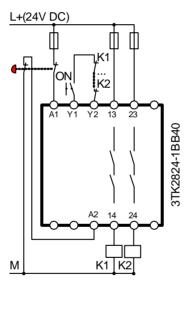


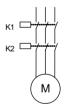


Not all faults are detected in the sensor circuit - e.g. a P fault in Y11 Y12 circuit, M fault in the Y21 Y22 circuit, when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.



Category 3 (acc. EN 954-1) E-Stop monitoring Stop-Category 0 2NO Vs 24 V DC manual start



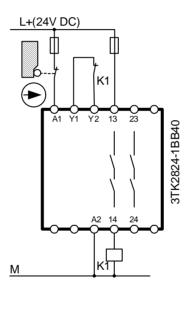


i

Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit. M fault in the A2 circuit, when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.



Category 2 (acc. EN 954-1) protective door monitoring Stop-Category 0 2NO Vs 24 V DC auto start





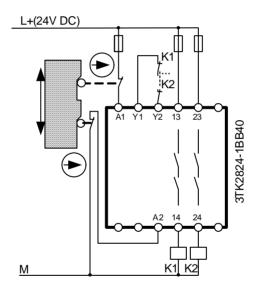


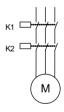
Not all faults are detected in the sensor circuit - e.g. a P fault in A1 circuit, when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.

⚠

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 3 (acc. EN 954-1) protective door monitoring Stop-Category 0 2NO Vs 24 V DC auto start



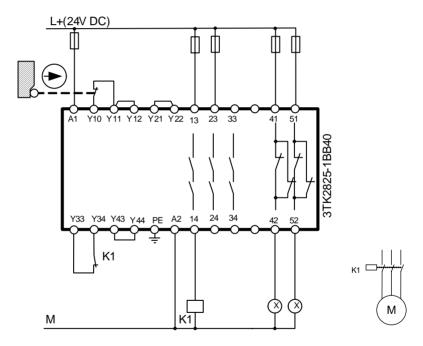


i

Not all faults are detected in the sensor circuit, e.g. a P fault in the A1 circuit, when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.



Category 2 (acc. EN 954-1) protective door monitoring Stop-Category 0 3NO 2NC Vs 24 V DC auto start



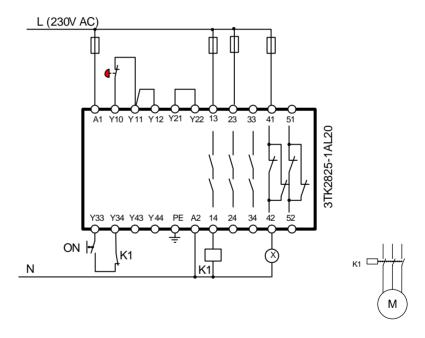
i

Not all faults are detected in the sensor circuit – e.g. a P fault in Y10 Y11 circuit, when a contact in the sensor welds. The user is responsible in ensuring that these types of faults do not occur.

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

3TK2825-1AL20

Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO 2NC Vs 230 V AC monitored start



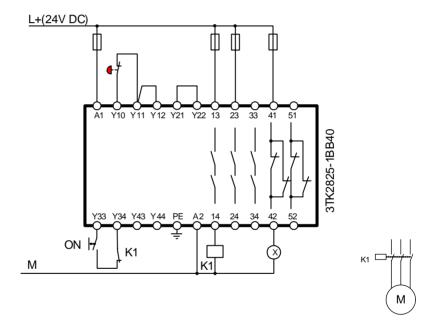


Not all faults are detected in the sensor circuit - e.g. a P fault in Y11 Y12 circuit, M fault in the Y21 Y22 circuit, when a contact in the sensor welds. The user is responsible in ensuring that these Types of faults do not occur.

Λ

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO 2NC Vs 24 V DC monitored start





Only safety-relevant sensors with positively-opening contacts may be used as sensors. Two oactuators (e.g. contactors) should be used in the load circuit.

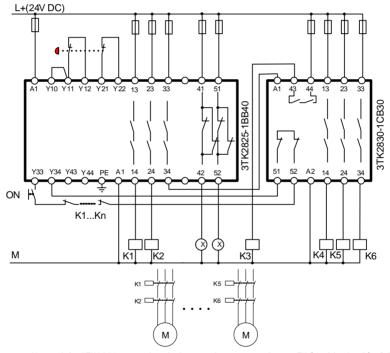
⚠

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

 3TK2825 + 3TK2830
 Category 4 (acc. EN 954-1)
 6NO 2NC

 E-Stop Monitoring
 Vs 24 V DC

 Stop-Category 0
 monitored start



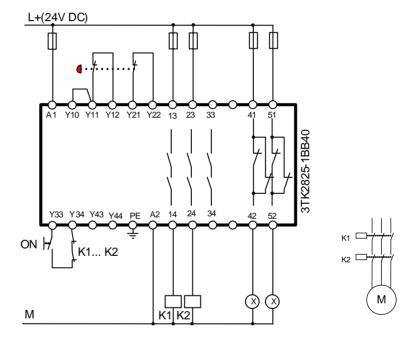


Up to eight 3TK2830 expansion devices can be connected to an FK (enable circuit) of the 3TK2825 basic device. When several expansion devices are cascaded, the response times must be added. When circuit faults are excluded – such as P fault or M fault – then it is permissible to control an expansion device through one channel (cascading). This condition is always fulfilled within a control cabinet or when connecting cables are routed in a protected fashion.

For Category 4, several EMERGENCY STOP commanding devices may be connected in series.



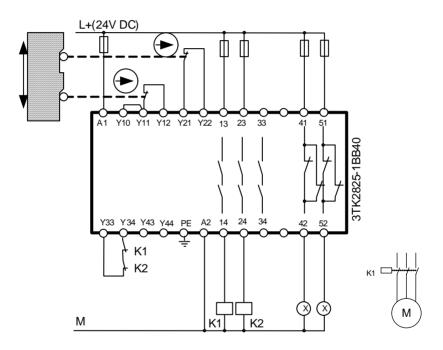
Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO 2NC Vs 24 V DC monitored start



For Category 4, several EMERGENCY STOP commanding devices may be connected in series.



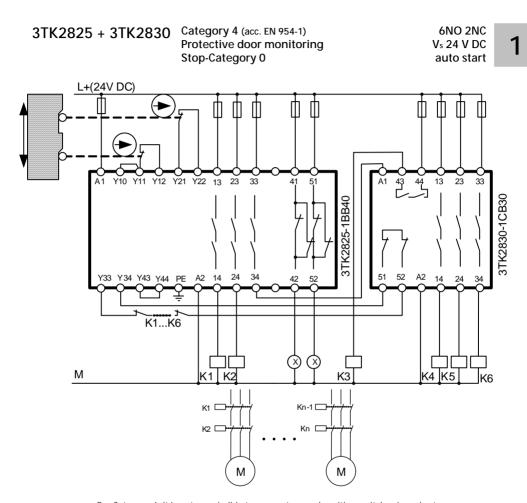
Category 4 (acc. EN 954-1) protective door monitoring Stop-Category 0 3NO 2NC Vs 24 V DC autostart





For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).





i

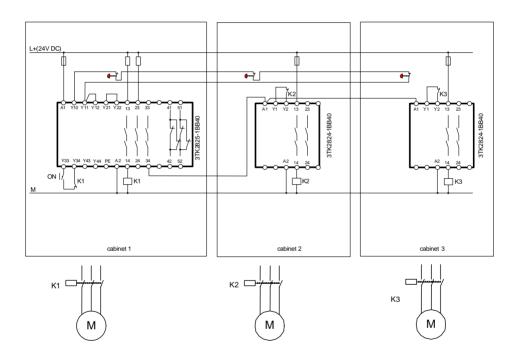
For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection). Up to eight 3TK2830 expansion devices can be connected to an FK (enable circuit) of the 3TK2825 basic device. When several expansion devices are cascaded, the response times must be added. When circuit faults are excluded – such as a P fault or a M fault – then it is permissible to control an expansion device through one channel (cascading). This condition is always fulfilled within a control cabinet or when connecting cables are routed in a protected fashion.



3TK2825 + 3TK2824 + 3TK2824 Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0

7NO 2NC Vs 24 V DC monitored start

E-Stop distributed over several cabinets



EMERGENCY STOP is monitored by a 3TK2825; the 3TK28 monitors the actuators in the same control cabinet. Always control the subsequent safety devices from the same, first safety device. The reason for this is that when several safety relays are used in series, the response times must be added. The 3TK2825 is required in order to maintain, e.g. a total response time of e.g. 200ms.



Only safety-relevant sensors with positively-opening contacts may be used as sensors. Tow actuators (e.g. contactors) should be used in the load circuit.



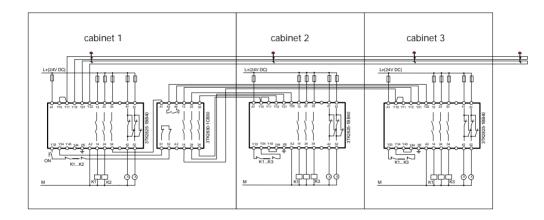
Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Safety relay

Function

8NO 6NC Vs 24 V DC monitored start

3TK2825 +	Category 4 (acc. EN 954-1)	
3TK2830 +	E-Stop Monitoring	
3TK2825 +	Stop-Category 0	
3TK2825	E-Stop distributed over several cabinets	



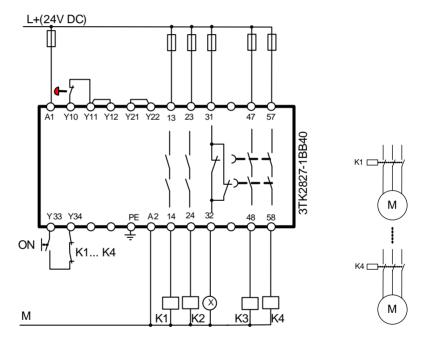
EMERGENCY STOP commanding devices are monitored by the 3TK2825 in cabinet 1: This is the reason that the response times do not have to be added. The actuators are monitored by the 3TK28 in the same control cabinet.



The 3TK2825 in cabinet 1 operates with a monitored start. The 3TK2825 in cabinets 2 and 3 operate with an automatic start. For Category 4, several EMERGENCY STOP commanding devices may be connected in series.



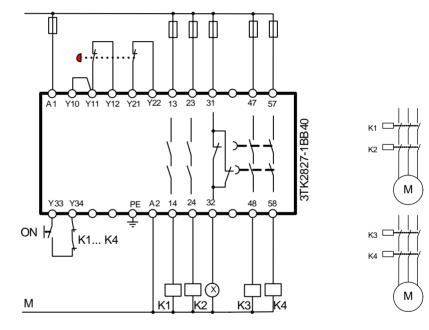
Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 and 1 2NO 2NOtv 1NC Vs 24 V DC monitored start



i

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 3/4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 and 1 2NO 2NOtv 1NC Vs 24 V DC monitored start





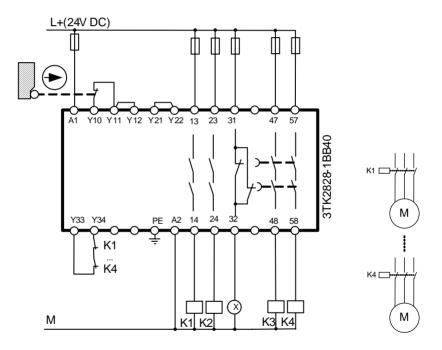
For Category 4, several EMERGENCY STOP commanding devices may be connected in series.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

The time-delayed outputs switch according to Category 3 in compliance with EN 954-1.

Category 2 (acc. EN 954-1) Protective door monitoring Stop-Category 0 and 1 2NO 2NOtv 1NC Vs 24 V DC auto start





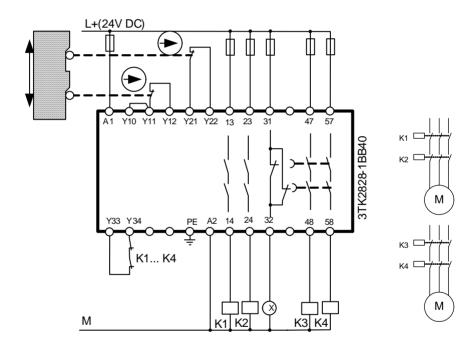
Tow actuators (e.g. contactors) should be used in the load circuit.

 $\mathbf{\Lambda}$

Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 3/4 (acc. EN 954-1) Protective door monitoring Stop-Category 0 and 1 2NO 2NOtv 1NC Vs 24 V DC auto start





i

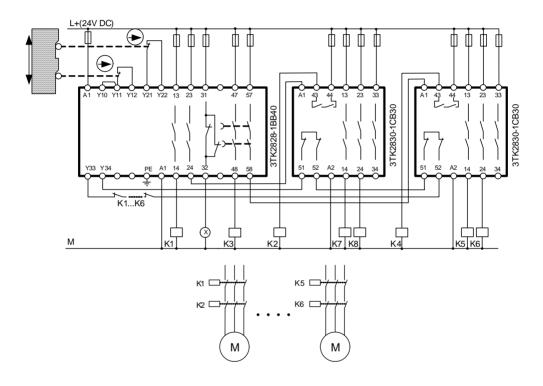
For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

The time-delayed outputs switch according to Category 3 in compliance with EN 954-1.

3TK2828 +	Category 3/4 (acc. EN 954-1)	4NO 4NOtv 1NC
3TK2830 +	Protective door monitoring	Vs 24 V DC
3TK2830	Stop-Category 0 and 1	auto start



For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection). Up to eight 3TK2830 expansion devices may be connected to an FK (enable circuit) of the basic 3TK2821 device.



When several expansion devices are cascaded, the response times must be added. When circuit faults are excluded – such as a P fault or a M fault – then it is permissible to control an expansion device through one channel (cascading). This condition is always fulfilled within a control cabinet or when connecting cables are routed in a protected fashion.

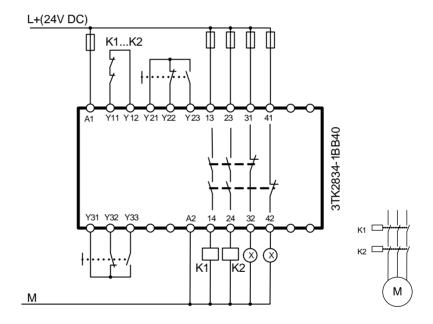


Function

3TK2834

Category 4 (acc. EN 954-1) Two hand Monitoring Stop-Category 0 2NO 2NC Vs 24 V DC two hand operating

Type III C (EN 574)

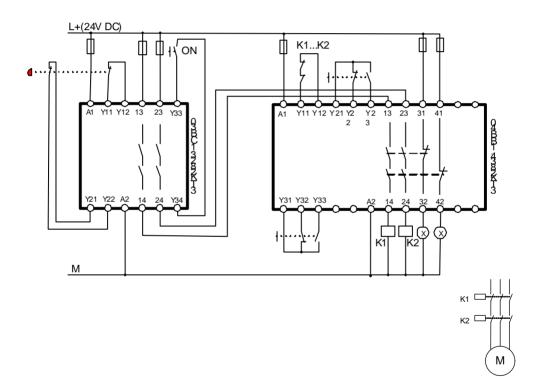




When the pushbuttons are simultaneously actuated within 500 ms then the safety relay is switched-in.

3TK2834 + 3TK2823 E-Stop and Two hand Monitoring Stop-Category 0 2NO 2NC Vs 24 V DC monitored start two hand operating

Type III C (EN 574)



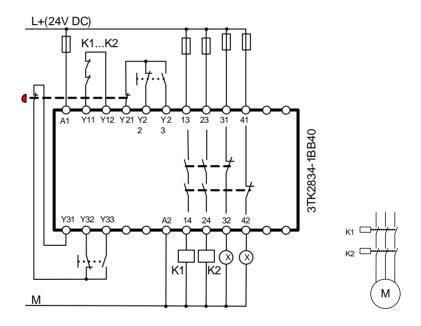


For Category 4, several EMERGENCY STOP commanding devices may be connected in series. When the pushbuttons are simultaneously actuated within 500 ms then the safety relay is switched-in.



Category 4 (acc. EN 954-1) E-Stop and Two hand Monitoring Stop-Category 0 2NO 2NC Vs 24 V DC monitored start two hand operating

Type III C (EN 574)





For Category 4, several EMERGENCY STOP commanding devices may be connected in series. Two hand operating with E-STOP Monitoring.

When the pushbuttons are simultaneously actuated within 500 ms then the safety relay is switched-in.

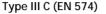


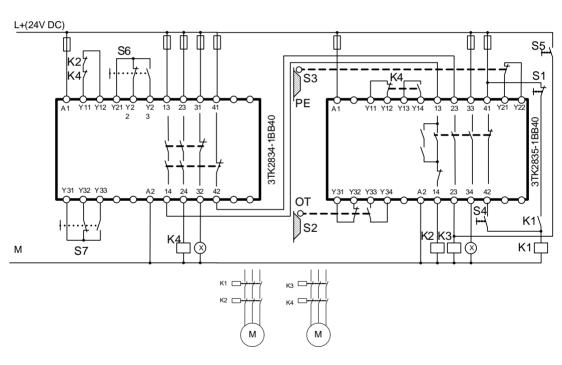
 3TK2834 + 3TK2835
 Category 4 (acc. EN 954-1)
 2NO 2NC

 Two hand Monitoring with
 Vs 24 V DC

 run-on distance check
 two hand operating

 Stop-Category 0
 Stop-Category 0







When the pushbuttons are simultaneously actuated within 500 ms then the safety relay is switched-in.

Sensor cables must be routed so that they are protected; only safety-relevant sensors with

positively-opening contacts may be used as sensors.

∧

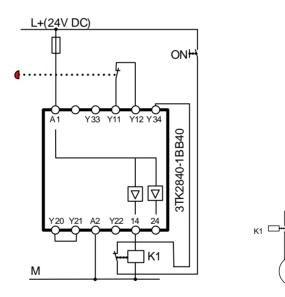
3TK284.

Safety relays with electronic outputs



Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 2NOel. Vs 24 V DC monitored start

Μ

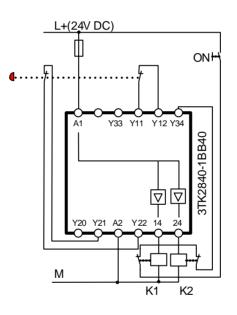


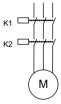


The output drivers (Sel) are only monitored via the external actuators – i.e. using the feedback circuit (Y34). This is the reason that this device may only be used in conjunction with positively-driven actuators.

Only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 2NOel. Vs 24 V DC monitored start





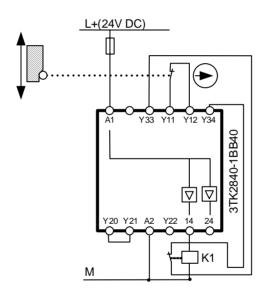


The output drivers (Sel) are only monitored via the external actuators – i.e. using the feedback circuit (Y34). This is the reason that this device may only be used in conjunction with positively-driven actuators.

For Category 4, several EMERGENCY STOP commanding devices may be connected in series.



Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 2NOel. Vs 24 V DC auto start





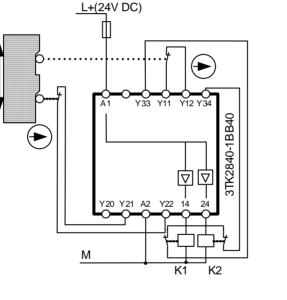


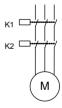
The output drivers (Sel) are only monitored via the external actuators – i.e. using the feedback circuit (Y34). This is the reason that this device may only be used in conjunction with positively-driven actuators.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0 2NO_{el.} Vs 24 V DC auto start







The output drivers (Sel) are only monitored via the external actuators – i.e. using the feedback circuit (Y34). This is the reason that this device may only be used in conjunction with positively-driven actuators.

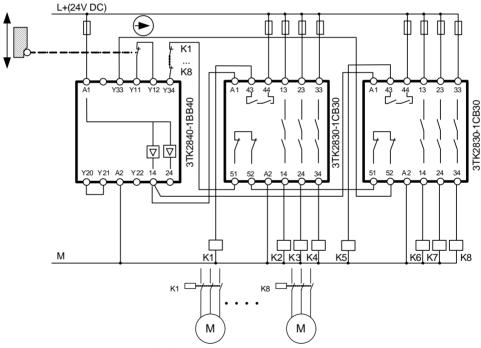
For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



3TK2840 + 3TK2830 + 3TK2830

2

Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 8NO Vs 24 V DC auto start



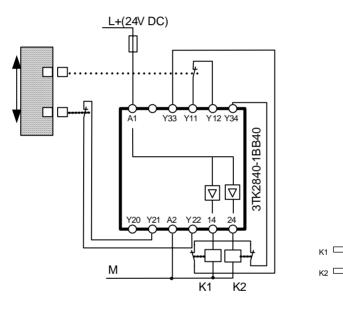


The output drivers (S_{el}) are only monitored via the external actuators – i.e. using the feedback circuit (Y34). This is the reason that this device may only be used in conjunction with positively-driven actuators.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 3 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0 2NO_{el.} Vs 24 V DC auto start





The output drivers (S_{el}) are only monitored via the external actuators – i.e. using the feedback circuit (Y34). This is the reason that this device may only be used in conjunction with positively-driven actuators.

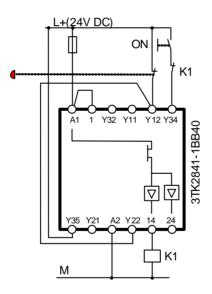


Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Using this circuit example, Category 2 according to EN 954-1 can only be fulfilled, if, when the actuator fails, either an alarm is automatically generated or the machine control initiates a safe condition. Otherwise a second shutdown path is required.

Μ

Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 2NOel Vs 24 V DC monitored start



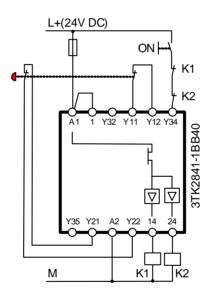


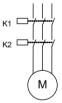




Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 2NOel Vs 24 V DC monitored start

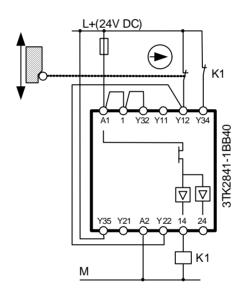






For Category 4, several EMERGENCY STOP commanding devices may be connected in series.

Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 2NOel Vs 24 V DC auto start

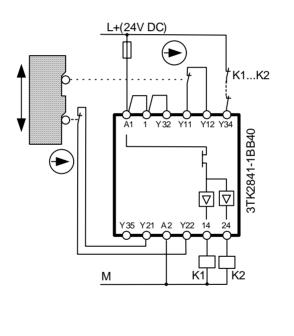


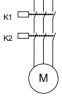




Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 2NOel Vs 24 V DC auto start



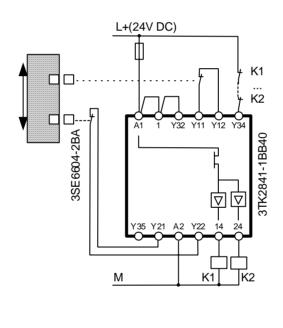


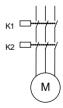


For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



3TK2841	Category 4 (acc. EN 954-1)	2NOel.
01112011	Magnet sensor Monitoring	Vs 24 V DC
	Stop-Category 0	auto start

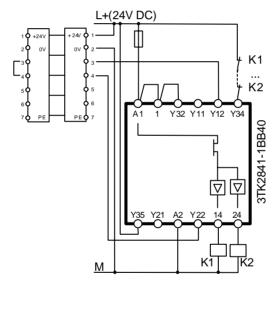


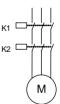


⚠

Category 4 (acc. EN 954-1) Light grid Monitoring Stop-Category 0

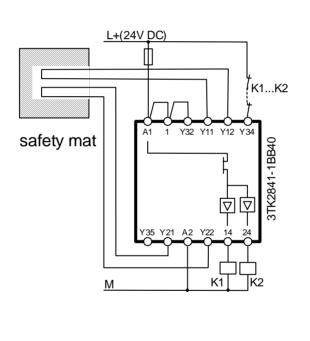
Light grid Type 4 (EN 61496-1) 2NOel. Vs 24 V DC auto start

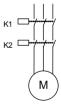






3TK2841	Category 3 (acc. EN 954-1)	2NOel.
	safety mat Monitoring	Vs 24 V DC
	Stop-Category 0	auto start



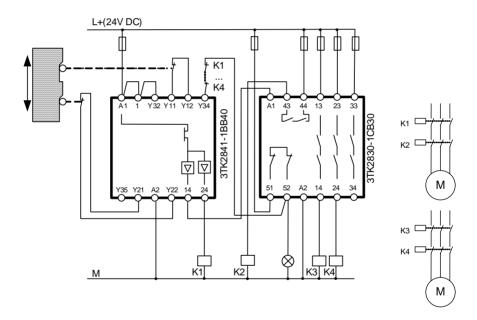




Category 3 according to EN 954-1 of this circuit is as a result of the safety mat.

Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 2NOel 5NC 1 signal lamp Vs 24 V DC auto start



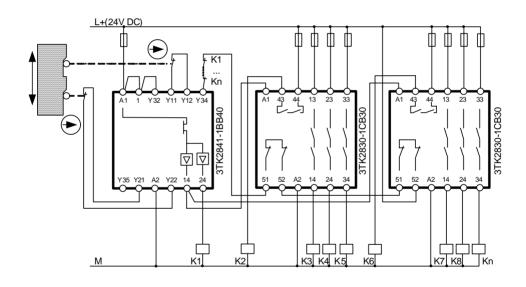




For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



3TK2841 + 3TK2830 + 3TK2830 Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 2NOel 6NO Vs 24 V DC auto start

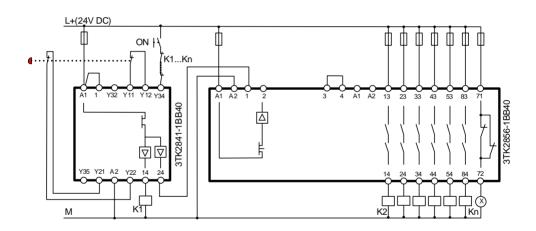




For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 2NOel 6NO 1NC Vs 24 V DC monitored Start



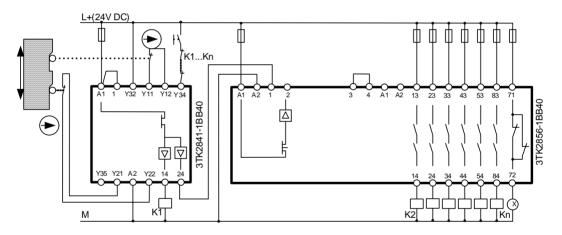


For Category 4, several EMERGENCY STOP commanding devices may be connected in series.

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Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 2NOel 6NO 1NC Vs 24 V DC auto start

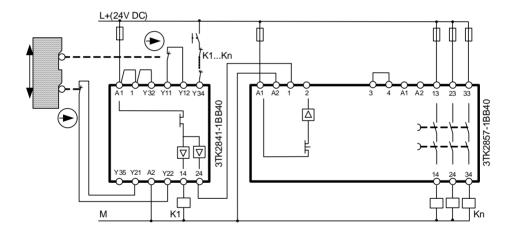




For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 and 1 2NOel 3NOtv Vs 24 V DC auto start





For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



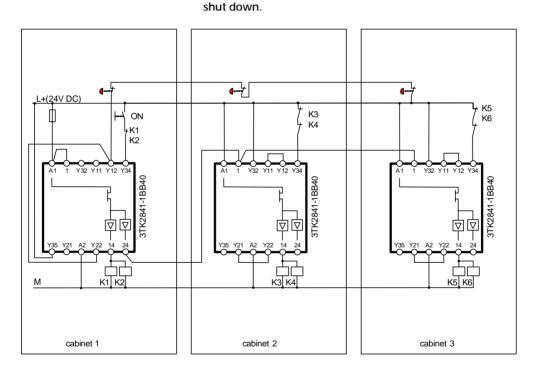
3TK2841 + 3TK2841 + 3TK2841 Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0

When an E-Stop button is pressed, all of the 3TK28 devices in the switchboard

3 Switchboards

3 E-Stop

6NOel Vs 24 V DC monitored start





Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Using this circuit example, Category 2 according to EN 954-1 can only be fulfilled, if, when the actuator fails, either an alarm is automatically generated or the machine control initiates a safe condition. Otherwise a second shutdown path is required.

Safety relay	Function	Comments
3TK2841 + 3TK2841 + 3TK2841	Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0	6NOel Vs 24 V DC monitored start
	3 Switchboards 3 E-Stop When an E-Stop button is pressed, all of the 3TK28 devices in the switchboard shut down.	
cabinet 1	cabinet 2	cabinet 3
L+(24V DC)	4- <u>4-</u> <u>4-</u> <u>4</u> -	● / / / / /
CN (K1 (K2	K3 K4	у к5 К6
V35 V21 A2 V22 V4 24 V35 V21 A2 V22 V4 A2 V22 V4 A2 V22 V4 A2 V4 A		V32 V21 V3 V22 V4 V32 V21 V32 V11 V12 V34 V32 V11 V12 V34 V32 V11 V12 V34 V32 V11 V12 V34 V32 V11 V12 V34 V33 V31 V12 V34 V34 V34 V34 V35 V21 V12 V34 V35 V31 V12 V34 V35 V35 V31 V12 V34 V35 V35 V34 V35 V35 V35 V35 V35 V35 V35 V35 V35 V35
M K1 K2	K3 K4	K5 K6



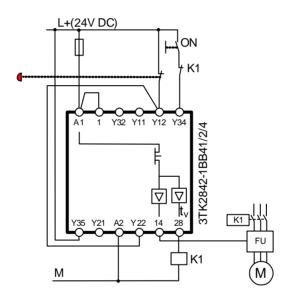
For Category 4, several EMERGENCY STOP commanding devices may be connected in series.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

2

Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 and 1 1NOel 1NOel tv Vs 24 V DC monitored start





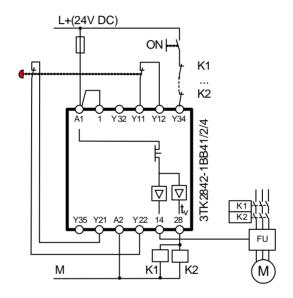
The controller enable of the frequency inverter is controlled directly – and the power contactor, with a time delay.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Using this circuit example, Category 2 according to EN 954-1 can only be fulfilled, if, when the actuator fails, either an alarm is automatically generated or the machine control initiates a safe condition. Otherwise a second shutdown path is required.

Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 and 1 1NOel 1NOel tv Vs 24 V DC monitored start

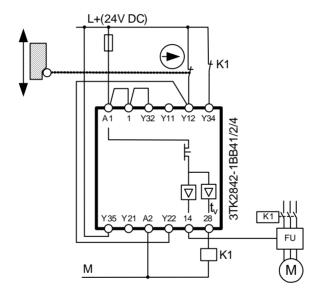




The controller enable of the frequency inverter is controlled directly – and the power contactor, with a time delay. For Category 4, several EMERGENCY STOP commanding devices may be connected in series.



Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 and 1 1NOel 1NOel tv Vs 24 V DC auto start





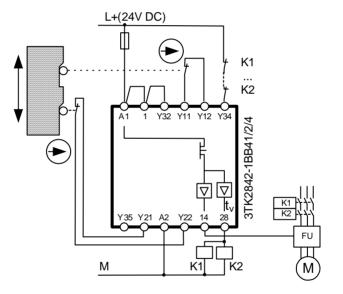
The controller enable of the frequency inverter is controlled directly – and the power contactor, with a time delay.



Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Using this circuit example, Category 2 according to EN 954-1 can only be fulfilled, if, when the actuator fails, either an alarm is automatically generated or the machine control initiates a safe condition. Otherwise a second shutdown path is required.

Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 and 1 1NOel 1NOel tv Vs 24 V DC auto start



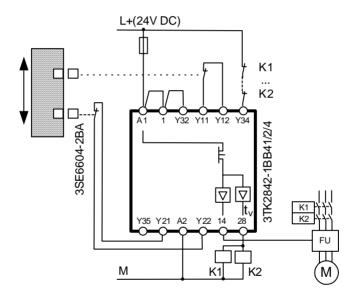


The controller enable of the frequency inverter is controlled directly – and the power contactor, with a time delay.

For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



Category 4 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0 and 1 1NOel 1NOel tv Vs 24 V DC auto start





The controller enable of the frequency inverter is controlled directly – and the power contactor, with a time delay.

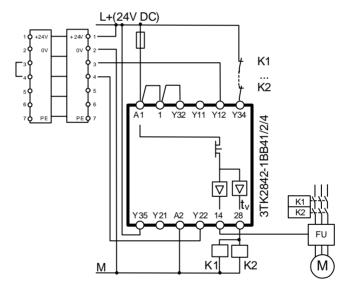
positively-opening contacts may be used as sensors.

Sensor cables must be routed so that they are protected; only safety-relevant sensors with

∧

Category 4 (acc. EN 954-1) Light grid Monitoring Stop-Category 0 and 1

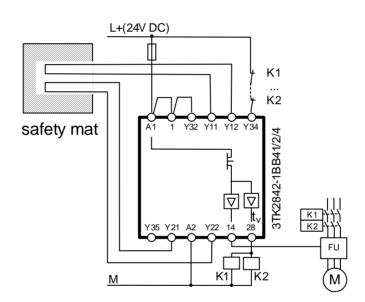
Light grid Type 4 (EN 61496-1) 1NOel 1NOel tv Vs 24 V DC auto start





The controller enable of the frequency inverter is controlled directly – and the power contactor, with a time delay.

Category 3 (acc. EN 954-1) Safety mat Monitoring Stop-Category 0 and 1 1NOel 1NOel tv Vs 24 V DC auto start





Category 3 according to EN 954-1 of this circuit is as a result of the safety mat. The controller enable of the frequency inverter is controlled directly – and the power contactor, with a time delay.

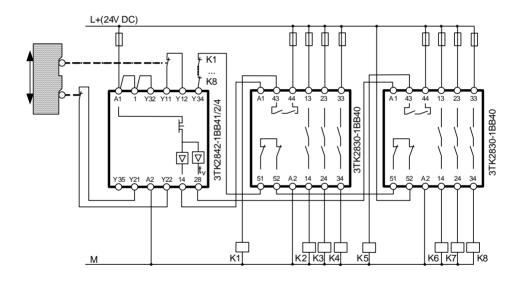


Function

3TK2842 + 3TK2830 + 3TK2830

Category 4 (acc. EN 954-1)
protective door
Monitoring
Stop-Category 0 and 1

4NO 4NOtv Vs 24 V DC auto start



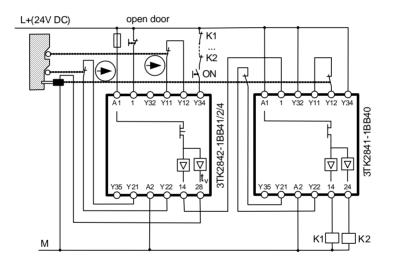


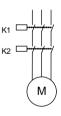
For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 and 1 2NOel 1NOel tv Vs 24 V DC monitored start

With interlocking, type-controlled







The tumbler mechanism of the position switch - interlocked with solenoid - is controlled with a time delay. For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



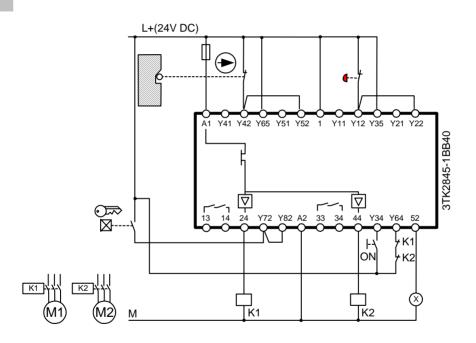
Safety relays with relays and electronic outputs



Category 2 (acc. EN 954-1) E-Stop and protective door Monitoring Stop-Category 0 2NO 2NOel 1Mel Vs 24 V DC manual start

Key-operated switch, that jumpers the protective door for the service mode



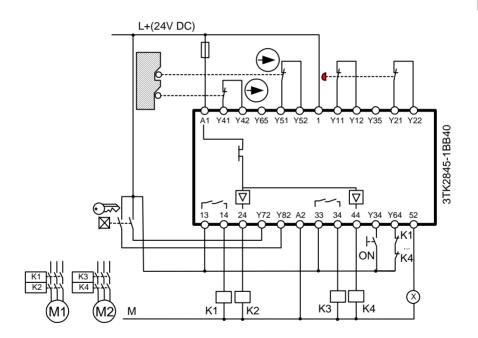


Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Using this circuit example, Category 2 according to EN 954-1 can only be fulfilled, if, when the actuator fails, either an alarm is automatically generated or the machine control initiates a safe condition. Otherwise a second shutdown path is required.

Category 4 (acc. EN 954-1) E-STOP and Protective door Monitoring Stop-Category 0

Key-operated switch, that jumpers the protective door for the service mode 2NO 2NOel 1Sel Vs 24 V DC monitored start



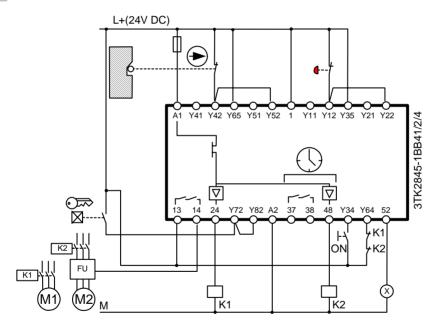
i

For Category 4, several EMERGENCY STOP commanding devices may be connected in series. For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



Category 2 (acc. EN 954-1) E-Stop and protective door Monitoring Stop-Category 0 and 1

Key-operated switch, that jumpers the protective door for the service mode 1NO 1NO_{el} / 1NO_{tv} 1NO_{el tv} /1S_{el} Vs 24 V DC manual start





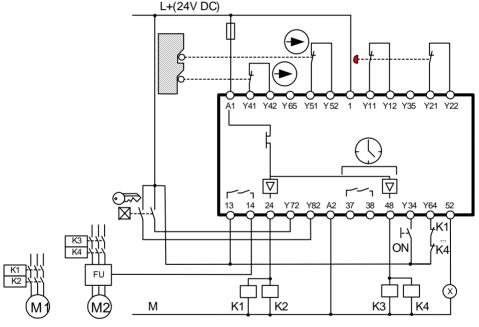
Category 4 (acc. EN 954-1) E-Stop and protective door Monitorina Stop-Category 0 and 1

Key-operated switch, that jumpers the protective door for the service mode

1NO 1NOel / 1NOty 1NOel tv /1Set V₅ 24 V DC monitored start



3TK2845-1BB41/2/4



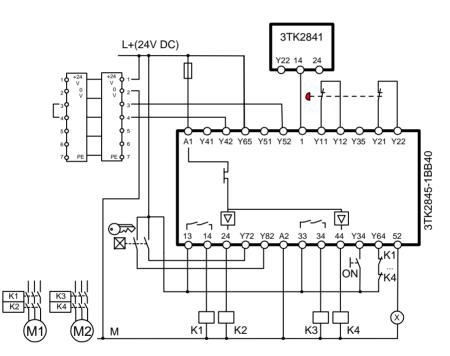


For Category 4, several EMERGENCY STOP commanding devices may be connected in series. For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



Category 4 (acc. EN 954-1) E-Stop and Light grid Monitoring Stop-Category 0

Key-operated switch, that bypasses the light grid type 4 (EN 61496-1) for service operation 2NO 2NOel 1Sel Vs 24 V DC monitored start



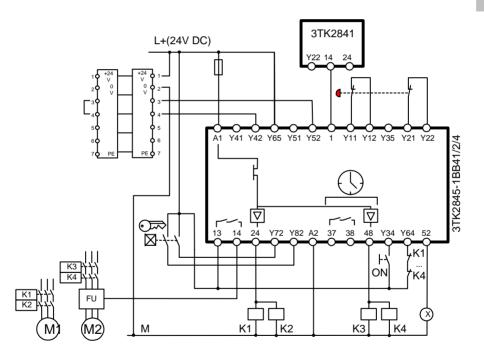


For Category 4, several EMERGENCY STOP commanding devices may be connected in series.



Category 4 (acc. EN 954-1) E-Stop and Light grid Monitoring Stop-Category 0 and 1

Key-operated switch, that bypasses the light grid type 4 (EN 61496-1) for service operation 1NO 1NO_{el} / 1NO_{tv} 1NO_{el tv} /1S_{el} Vs 24 V DC monitored start



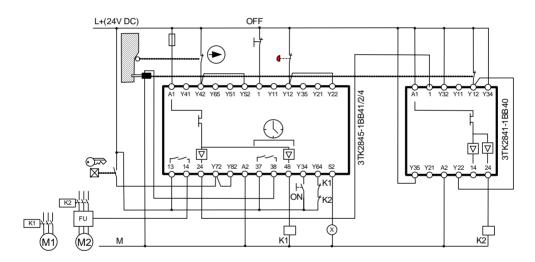


For Category 4, several EMERGENCY STOP commanding devices may be connected in series.



Category 2 (acc. EN 954-1) E-Stop and protective door Monitoring Stop-Category 0 and 1 1NO 2NOel / 1NOtv 1NOel tv /1Sel Vs 24 V DC manual start

Key-operated switch, that jumpers the protective door for the service mode



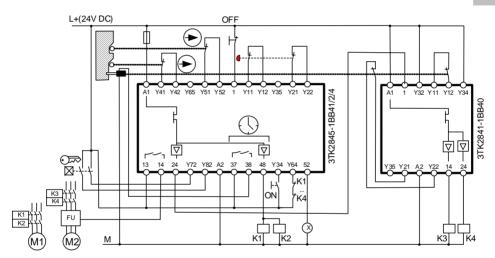


The tumbler mechanism of the position switch - interlocked with solenoid - is controlled with a time delay.



Category 4 (acc. EN 954-1) E-Stop and protective door Monitoring Stop-Category 0 and 1 1NO 2NO_{el} / 1NO_{tv} 1NO_{el tv} /1S_{el} Vs 24 V DC monitored start

Key-operated switch, that jumpers the protective door for the service mode



H

The tumbler mechanism of the position switch - interlocked with solenoid - is controlled with a time delay. Two load contactors in a cabinet for Category 4 acc. to EN 954-1 may be connected to an enable circuit (a short-circuit fault can be excluded). For Category 4, several EMERGENCY STOP commanding devices may be connected in series.

For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



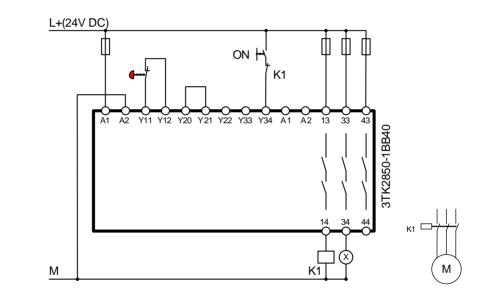
3TK285.

Safety relays with auxiliary relays



Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO Vs 24 V DC monitored start

Signaling using SIRIUS accessories



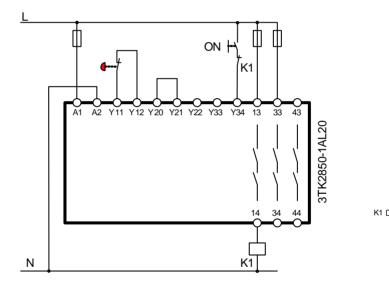


4 - 2

3TK2850-1LA20

Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO Vs 230 V AC monitored start

Signaling using SIRIUS accessories



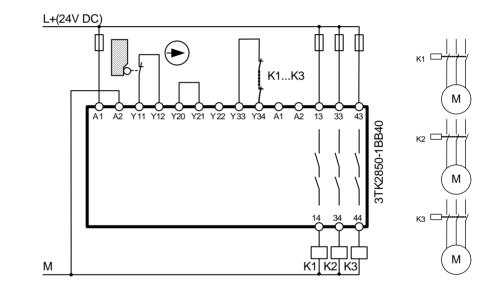
4

Μ



Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 3NO Vs 24 V DC auto start

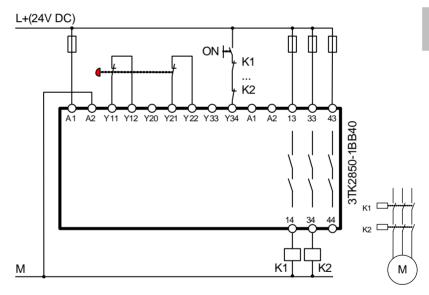
Signaling using SIRIUS accessories





Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO Vs 24 V DC monitored start

Signaling using SIRIUS accessories



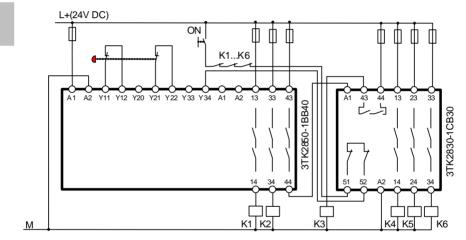


Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

4

Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 6NO Vs 24 V DC monitored start

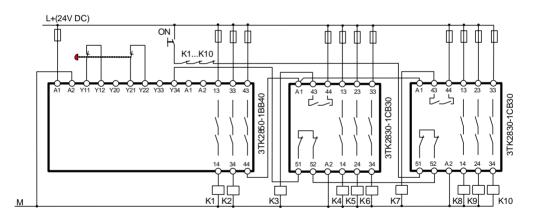
Signaling using SIRIUS accessories





3TK2850 + 3TK2830 + 3TK2830 Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 10S Vs 24 V DC monitored start

Signaling using SIRIUS accessories





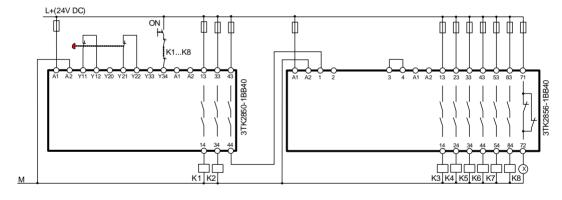
Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Δ

3TK2850 + 3TK2856 Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 8S 1NC Vs 24 V DC monitored start

Signaling using SIRIUS accessories

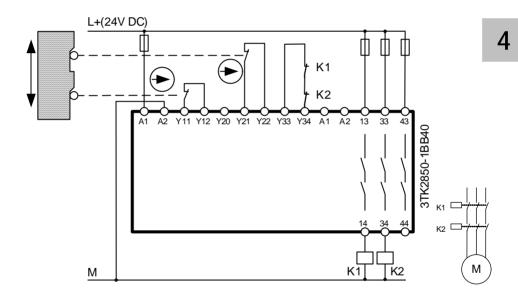






Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0 3NO Vs 24 V DC auto start

Signaling using SIRIUS accessories

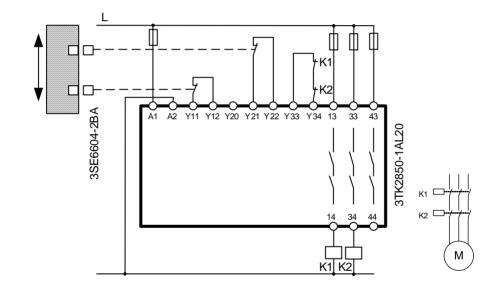




3TK2850-1LA20

Category 3 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0 3NO Vs 230 V AC auto start

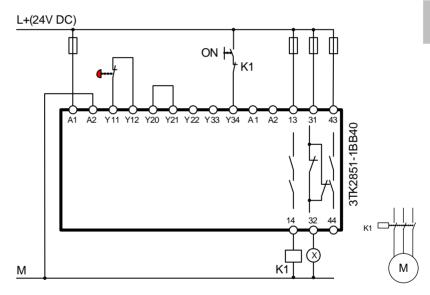
Signaling using SIRIUS accessories





Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 2NO 1NC Vs 24 V DC monitored start

Signaling using SIRIUS accessories



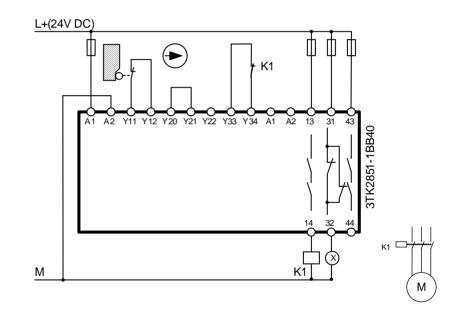


Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

Δ

Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 2NO 1NC Vs 24 V DC auto start

Signaling using SIRIUS accessories



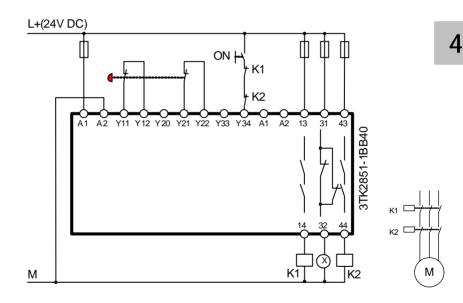


Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

4

Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 2NO 1NC Vs 24 V DC monitored start

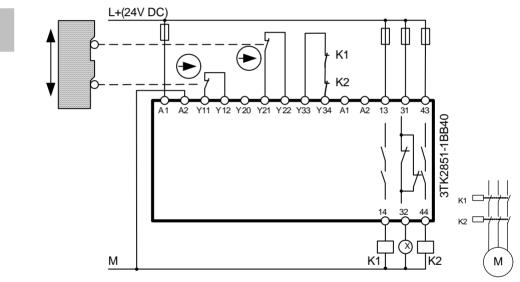
Signaling using SIRIUS accessories





Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0 2NO 1NC Vs 24 V DC auto start

Signaling using SIRIUS accessories

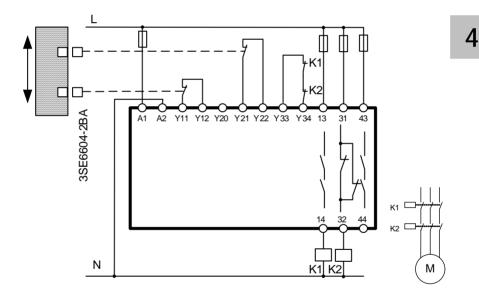




3TK2851-1LA20

Category 3 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0 2NO 1NC Vs 230 V AC auto start

Signaling using SIRIUS accessories



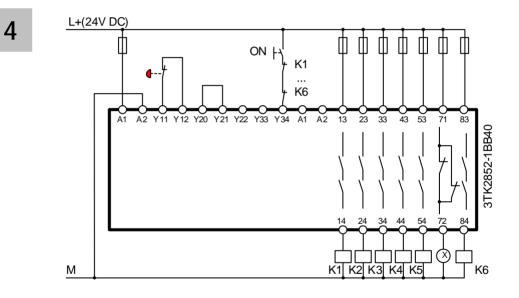


Sensor cables must be routed so that they are protected; only safety-relevant sensors with positively-opening contacts may be used as sensors.

4 - 15

Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 6NO 1NC Vs 24 V DC monitored start

Signaling using SIRIUS accessories



Sensor cables must be routed so that they are protected; only safety-relevant sensors with

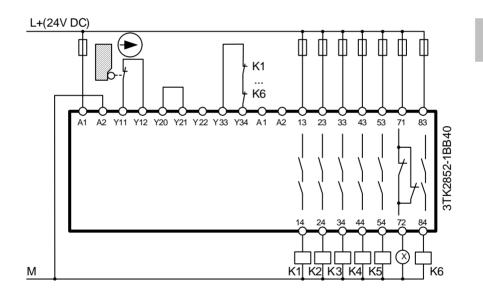
positively-opening contacts may be used as sensors.

⚠

Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 6NO 1NC Vs 24 V DC auto start

4

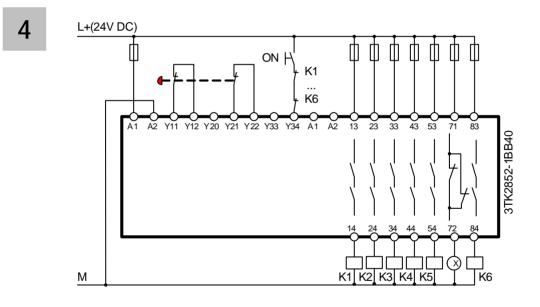
Signaling using SIRIUS accessories





Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 6NO 1NC Vs 24 V DC monitored start

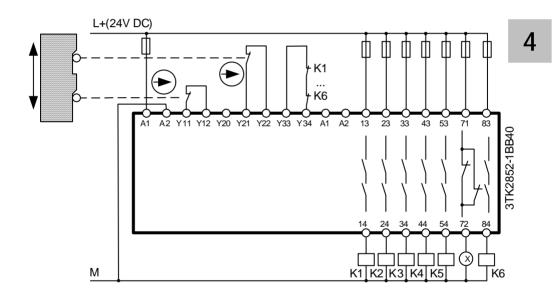
Signaling using SIRIUS accessories





Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0 6NO 1NC Vs 24 V DC auto start

Signaling using SIRIUS accessories

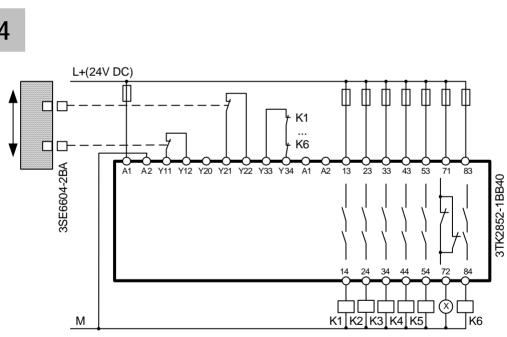




Category 3 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0

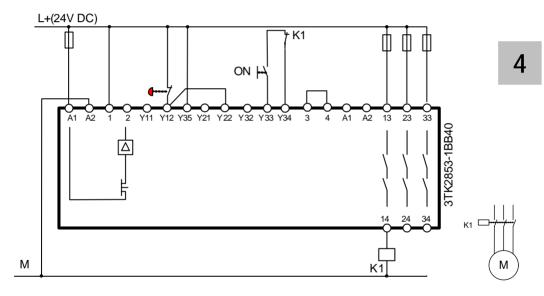
6NO 1NC Vs 24 V DC auto start

Signaling using SIRIUS accessories



Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC monitored start

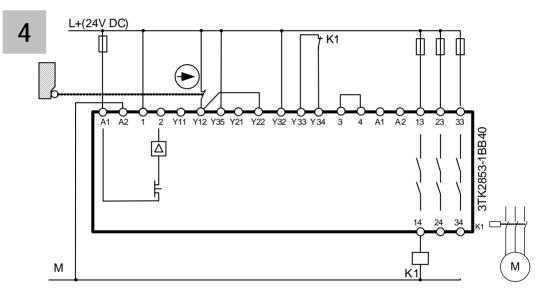
Signaling using SIRIUS accessories





Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

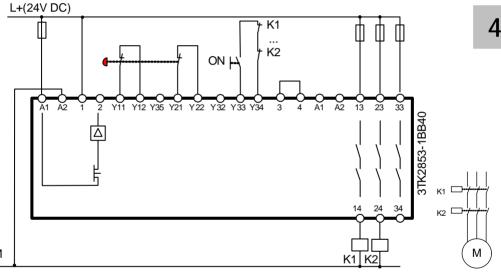
Signaling using SIRIUS accessories





Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC monitored start

Signaling using SIRIUS accessories

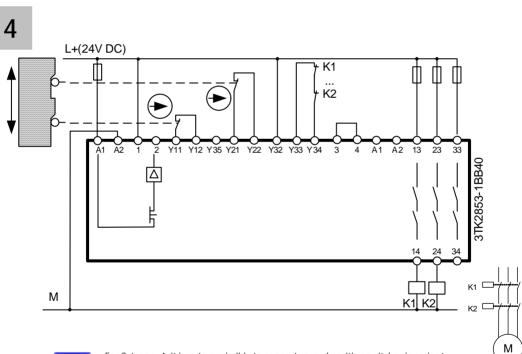






Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

Signaling using SIRIUS accessories



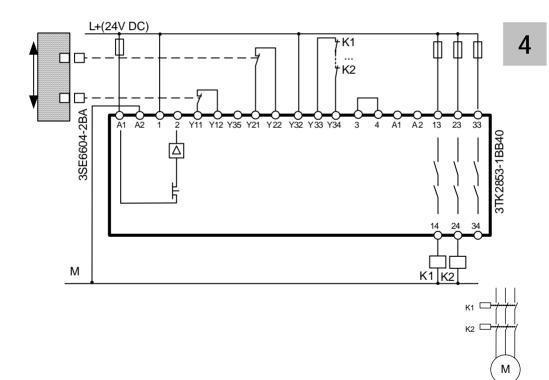


For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



Category 4 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

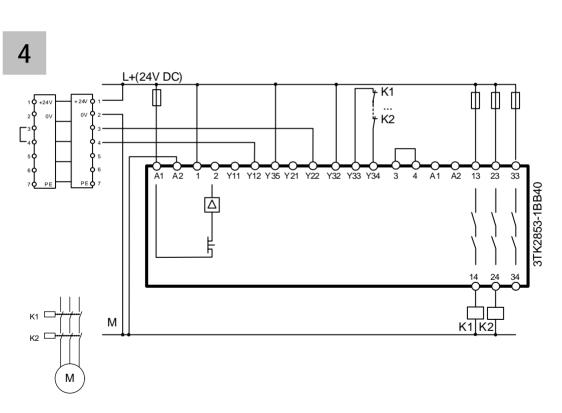
Signaling using SIRIUS accessories



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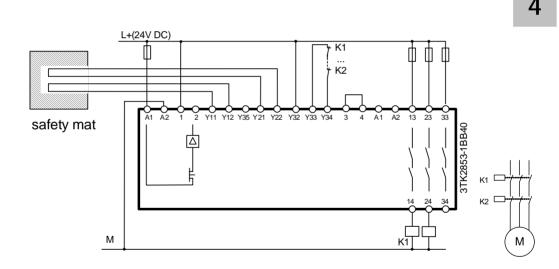
Category 4 (acc. EN 954-1) Light grid Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

Signaling using SIRIUS accessories



Category 3 (acc. EN 954-1) Safety mat Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

Signaling using SIRIUS accessories

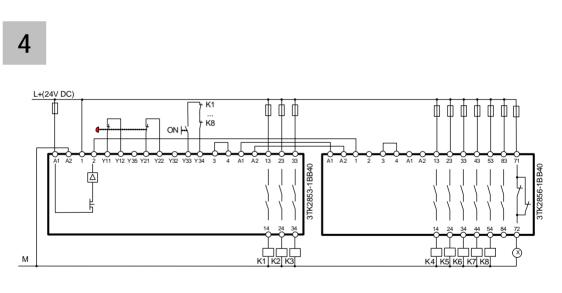


Category 3 according to EN 954-1 of this circuit is as a result of the safety mat.



3TK2853 + 3TK2856 Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 9NO 1NOel Vs 24 V DC monitored start

Signaling using SIRIUS accessories



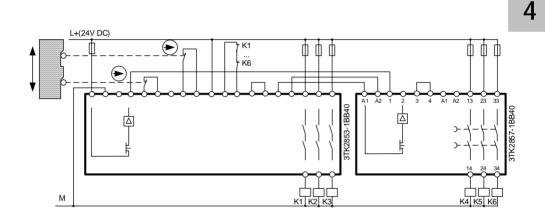


For Category 4, several EMERGENCY STOP commanding devices may be connected in series.

Λ

3TK2853 + 3TK2857 Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 3NO 1NOel 3NOtv Vs 24 V DC auto start

Signaling using SIRIUS accessories





For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



3RA71.

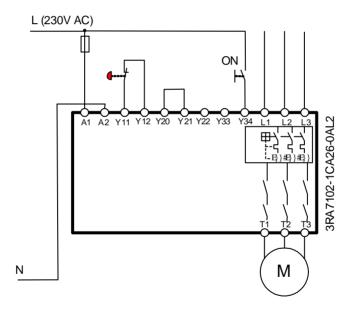
Safe load feeders





Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO Vs 230 V AC monitored start

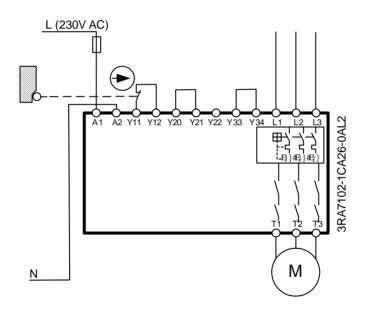
Signaling using SIRIUS accessories





Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 3NO Vs 230 V AC auto start

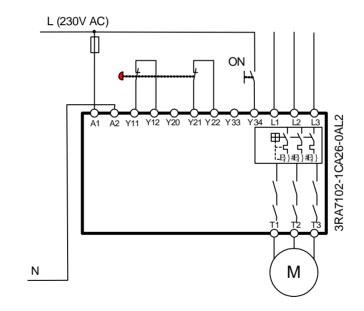
Signaling using SIRIUS accessories





Category 3 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO Vs 230 V AC monitored start

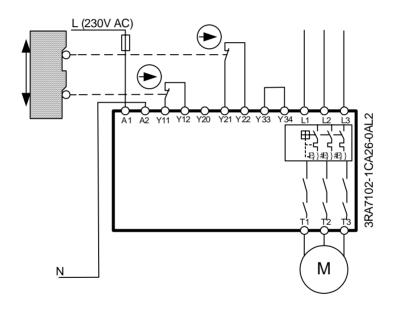
Signaling using SIRIUS accessories



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Category 3 (acc. EN 954-1) protective door Monitoring Stop-Category 0 3NO Vs 230 V AC auto start

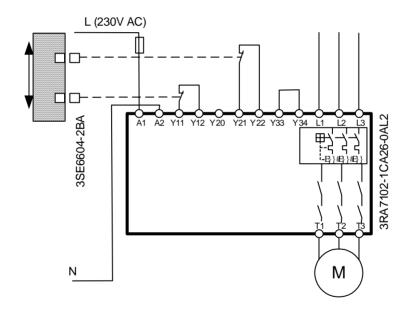
Signaling using SIRIUS accessories





Category 3 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0 3NO Vs 230 V AC auto start

Signaling using SIRIUS accessories



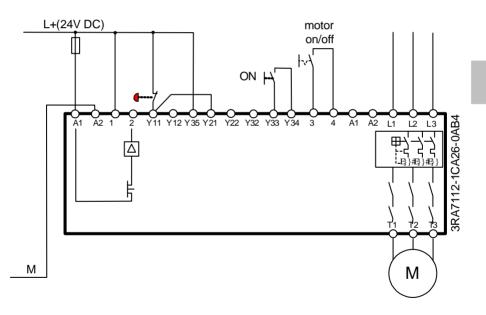
Sensor cables must be routed so that they are protected; only safety-relevant sensors with

positively-opening contacts may be used as sensors.

⚠

Category 2 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC monitored start

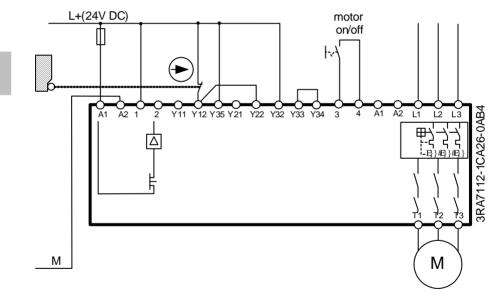
Signaling using SIRIUS accessories





Category 2 (acc. EN 954-1) protective door Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

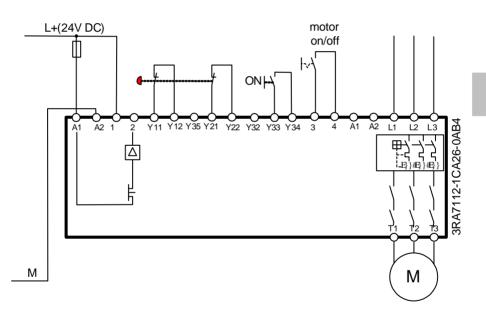
Signaling using SIRIUS accessories





Category 4 (acc. EN 954-1) E-Stop Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC monitored start

Signaling using SIRIUS accessories

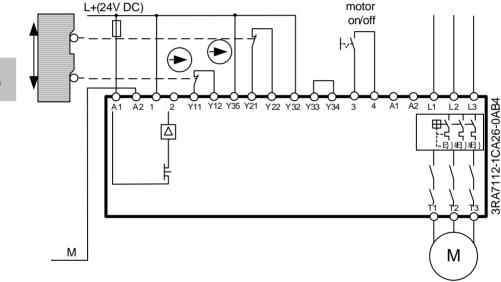




For Category 4, several EMERGENCY STOP commanding devices may be connected in series.

Category 4 (acc. EN 954-1) protective door Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

Signaling using SIRIUS accessories



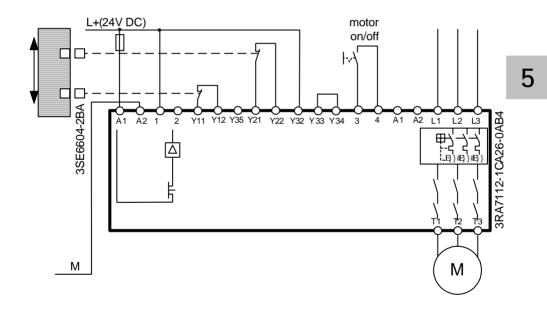


For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).



Category 4 (acc. EN 954-1) Magnet sensor Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

Signaling using SIRIUS accessories

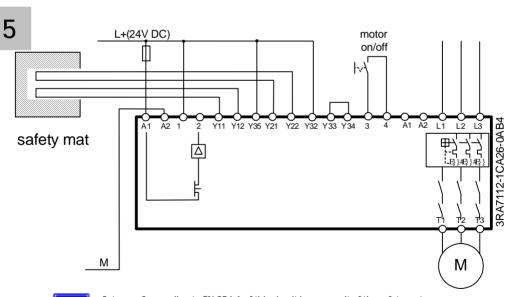






Category 3 (acc. EN 954-1) Safety mat Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

Signaling using SIRIUS accessories



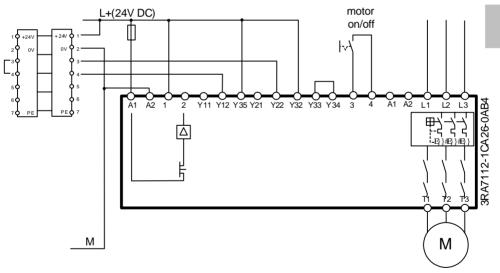


Category 3 according to EN 954-1 of this circuit is as a result of the safety mat.

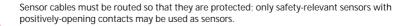


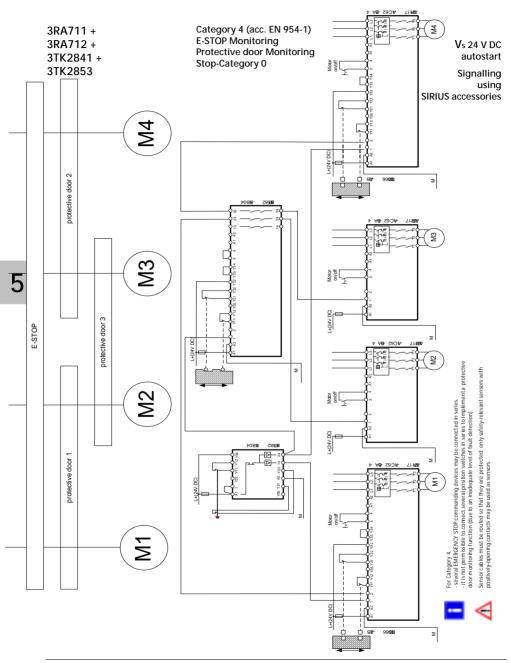
Category 4 (acc. EN 954-1) Light grid Monitoring Stop-Category 0 3NO 1NOel Vs 24 V DC auto start

Light grid Type 4 (EN 61496-1) Signaling using SIRIUS accessories



i





SIRIUS Safety Integrated Application Manual – S.I.A.M. – Edition 02/2005

ANNEX

Categories acc. to EN 954-1

For safety-relevant parts and components of control systems, potential risks are evaluated that are classified in Categories B and 1 to 4 acc. to EN 954-1. This classification should not be considered a hierarchic classification!

A simplified representation can be considered as follows:

	Brief summary of the requirements	System behavior	Principle	
4	Requirements of B must be fulfilled; a single fault must be detected before or at the next demand upon the safety function.	When faults occur, the safety function is always performed; the faults are detected in time to prevent the loss of the safety function.	Mainly characterized by the structure of the control	
3	Requirements of B must be fulfilled, a single fault may not lead to the loss of the safety function; single faults must be detected	The safety function is always performed when single faults occur		
2	Requirements of B must be fulfilled; the safety function shall be checked , additionally at suitable time intervals.	The occurrence of a fault can lead to the loss of the safety function between the checks.		
1	Requirements of B must be fulfilled; well-proven components and safety principles shall be used.	The same system behavior as B, however with a higher safety-relevant reliability	Mainly characterized by the selection of components	
B	The control must be designed so that it can withstand the expected influences	The occurrence of one fault can lead to the loss of the safety function		

The categories are not hierarchic

A risk analysis determines the danger and the resulting hazard. This hazard represents a risk for man, machine and the environment. This risk can be reduced to a residual risk (minimized) by applying suitable measures. The residual risk that can be tolerated requires, among others, external measures (e.g. a protective fence) and an appropriate Category for the safety-relevant parts of the control system!

Example:

There is a hazard, e.g. as a result of a robot (in a machining cell), that could injure a person if he or she enters the hazardous zone (this could also result in death). There are two possible solutions:

Protective measure A: A protective fence without protective door (and without any other possibility of erected accessing the hazardous zone) is around the cell with the robot. This prevents access to this hazardous zone. This means that there is an extremely low residual risk: This corresponds to Category 1. However, the disadvantage of this solution is that it takes considerable effort to enter the cell with the robot (e.g. when carrying-out maintenance work).

Protective measure B: A protective fence with a protective door (this being the only access possibility) is erected around the robot cell. When the protective door is opened, the robot is brought into a safe condition.

This means that the residual risk corresponds to Category 3; this is because the operator may not be injured if he wishes to regularly enter the cell with the robot.

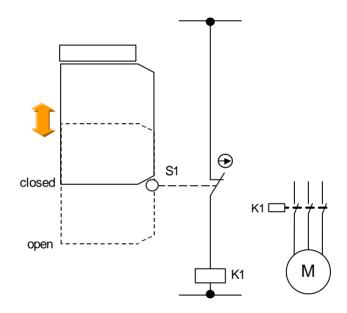
The increase of the degree of safety using additional measures – e.g. by overdimensioning the load contactors – does not result in a higher Category!

This does not result in a fault exclusion!

EN 954-1

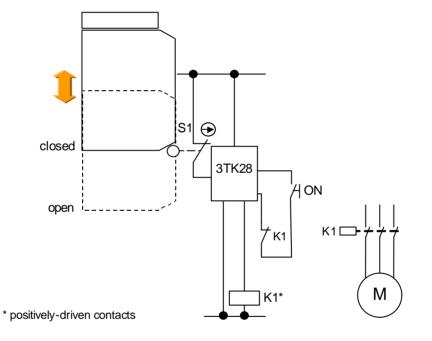
FN 954-1

Category 1 acc. EN 954-1

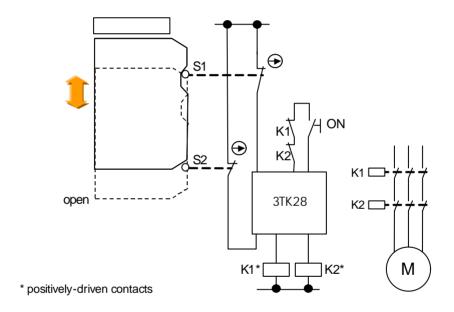


Δ

Category 2 acc. EN 954-1



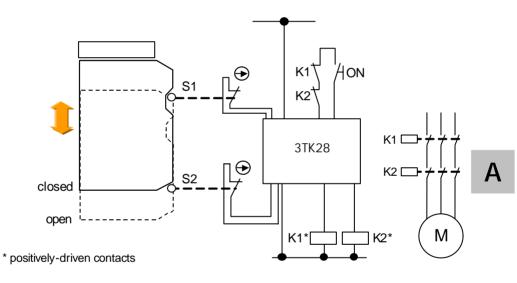
Category 3 acc. EN 954-1



A - 6

Α

Category 4 acc. EN 954-1

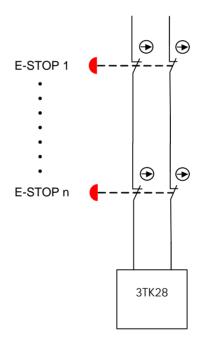


Serial connection E-STOP command element

EN 954-1 ISO 12100-1 (EN 292-1)

up to category 4

EMERGENCY STOP command devices may always be connected in series: It can be excluded that the EMERGENCY STOP devices fail and are simultaneously actuated.



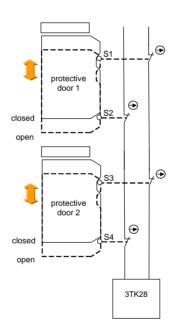
Serial connection Pro

Protective door monitoring

EN 954-1 ISO 12100-1 (EN 292-1)

up to category 3

Position switches may be connected in series if several protective doors are not regularly and simultaneously opened (as otherwise faults cannot be detected).





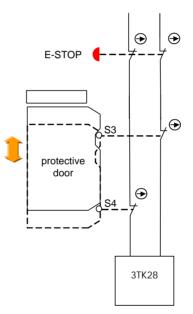
For Category 4, it is not permissible to connect several position switches in series to implement a protective door monitoring function (due to an inadequate level of fault detection).

Serial connection

up to category 3

E-Stop command element and protective door monitoring EN 954-1 ISO 12100-1 (EN 292-1)

E-Stop command elements and position switches may be connected in series if several protective doors are not regularly and simultaneously opened and E-Stop is actuated (as otherwise faults cannot be detected).



Α



For Category 4, it is not permissible to connect several position switches and E-Stop command elements in series to implement a protective door monitoring function (due to an inadequate level of fault detection).

device: An unexpected start must be completely excluded.

Manual start, monitored start and auto start

A safety relay can be manually monitored or automatically started.

For a **manual** or **monitored** start, when pressing the ON button – after checking the input image and after a positive test of the safety relay, an enable signal is generated. This function is also designated as static operation and is specified for EMERGENCY STOP devices (EN 60204-1, conscious action).

This is possible with the

various safety relays.

Contrary to a manual start, the monitored start evaluates a signal change of the ON button. This means that the actuation of the ON button cannot be tampered/ manipulated with.

For an **automatic start**, without a manual agreement, but after the input image has been checked and a positive test of the safety relay, an enable signal is generated.

This function is also designated as dynamic operation and is not permissible for EMERGENCY STOP devices. Protective devices that cannot be entered but mechanically isolate (e.g. guard) operate with an automatic start.

Comment: A manual start can be implemented with a safety relay with automatic start, if, in the feedback circuit, in addition to the positively-opening contacts of the load contactors, an ON button is additionally connected in series.

Manual start is possible up to Category 3.	This is possible with safety relays with automatic start.	EN 954-1
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A manual start is permissible for an EMERGENCY STOP device up to Category 3 according to EN 954-1 (ISO 13849-1).

For Category 4 according to EN 954-1 (ISO 13849-1), a monitored start is necessary for an EMERGENCY STOP

Monitored start is necessary from Category 4.

This is possible with safety relays with monitored start EN 954-1



EN 954-1

Safety-relevant (protected) routing, safe separation

The objective is to achieve a high degree of operational safety.

In order to protect against parasitic (vagabond) voltages, the different voltages in a cable or piece of equipment must be insulated with respect to the highest voltage present

(protection against electric shock, IEC 61140):

cable insulation between cables/conductors at different potentials;

 \downarrow AS-i modules must fulfill, between AS-i interface and V_{auxillary} the requirements according to EN 50187 regarding the air and creepage distances and the voltage strength of the insulation of the relevant parts and components.

Protective door monitoring with tumbler mechanism

Non-safety-relevant control of the tumbler mechanism is possible up to Category 3

Safety-relevant control of the tumbler mechanism is required from Category 4

A

The objective of a tumbler mechanism is to maintain an isolating, protective device (e.g. guard) in the closed position.

. The tumbler mechanism must be connected with the control so that

a) The isolating, protective device may only be opened if there is no motion present in the machine that is potentially hazardous,

b) The machine may only start when the isolating, protective device (e.g. guard) is closed and is interlocked. *Comment:*

∉# Up to Category 3 according to EN 954-1

(ISO 13849-1), the tumbler mechanism does not have to be controlled in a safetyrelevant fashion.

For Category 4 according to EN 954-1 (ISO 13849-1), the control must always be realized in a safety-relevant fashion.

The position monitoring of the interlocking device (solenoid) must, from Category 3 onwards, be individually monitored according to EN 954-1 (ISO 13849-1) – and may not be switched in series with the monitoring of the separate actuator (due to the poor level of fault detection).

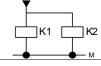
One output for category 3 and 4 with two switch gears

(fault due to short circuit can be excluded)

One safety-related output can be used in the cabinet

to actuate one or more switch gears up to category 4 according to EN 954-1

output of safety relay



FN 954-1

EN 954-1 ISO 12100-1 (EN 292-1) EN 60204-1

IEC 61140-1

FN 50187

Technical Assistance for low-voltage switchgear

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NOTICES

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Because:			
Time saving by u	using the document:		
No saving f	approx. 5% £	approx. 10% £	other%
Suggestions / re	ecommendations:		

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